Notions of Mechanism Design

Static Adverse Selection 0000 00000000000 Dynamic Adverse Selection

Macroeconomics and Public Finance: Static and Dynamic Models of Adverse Selection

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Economic of Information and Macroeconomics

- Asymmetric Information is pervasive in economics
- Industrial Organization and Market Structure
- Financial Crisis: Adverse Selection and Moral Hazard
- Designing Institutions:
 - Firms and Markets
 - Optimal Taxation and Public Finance
- Nobel Prizes: Horowiz, Myerson, and Mirrleese
- Macroeconomics Focuses on Dynamic Aspects and Institution Design

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Economic of Information and Macroeconomics II

- Agents can save and borrow
- Markets Available to Agents
- Questions of Modern (Macro) Public Finance:
 - Capital Taxation
 - Social Insurance and Welfare Programs
 - Subor Income Taxes over the Life Cycle
 - Education Taxes and Subsidies

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Mechanism Design and Bayesian Games

- Bayesian Games $\Gamma = < N, T, S, X, M, U, P >$
 - N= set of players
 - S_i Strategy agent *i*: $S = \prod_i S_i$
 - X= set of outcomes
- Def. 1: A Comunication Mechanism is a a rule

$$M: S \to \Delta(X)$$

- Nature chooses type t_i from P (common knowledge)
- Preferences: $U_i(t, x)$

Def. 2: A pure strategy is a function:

$$\sigma_i: T_i \to S_i$$

$$\sum_{i=i}^{n} P(t_{-i}|t_i) U_i(t, M(s))$$

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Bayesian-Nash Equilibrium

Def. 3: σ^* is a Bayesian-Nash (B-N) Equilibrium of Γ if for each t_i and for all $\sigma_i(t_i)$: (Incentive Compatibility)

$$\sum_{t_{-i}} P(t_{-i}|t_i) U_i(t, M(\sigma_i^*(t_i), \sigma_{-i}^*(t_{-i})))$$

$$\geq \sum_{t_{-i}} P(t_{-i}|t_i) U_i(t, M(\sigma_i(t_i), \sigma_{-i}^*(t_{-i})))$$

Example: Auction

- $X = N x R_+$ Allocation of goods and payments (w, m)
- $S_i = R_+$ Bids
- Mechanism=Auction: $M(s) \rightarrow (w, m)$
- $w = \arg \max_i s_i$
- $m = \max_i s_i$ (first price); $m = \max_{i \neq w} s_i$ (second price)
- $U_w(w, m) = V_w m$ and $U_j = 0$ if $j \neq w$
- For example, V_i is independent uniform on [0, 1] ($T = [0, 1]^n$) Exercise 1: Compute optimal strategies and B-N equilibria for first price

Exercise 1: Compute optimal strategies and B-IV equilibria for first price auction. [Hint: $\max_b(V-b) \Pr(b > \max_{j \neq i} b^*(V_j))$]

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The Revelation Principle

- Def. 4: A game Γ^D is direct if $S_i = T_i$. A direct mechanism M^D is a mechanism of a direct game
- Theorem: (e.g., Myerson (1979-1984)) For any B-N equilibrium σ^* of a game Γ there exists a direct game such that truthtelling: $\sigma_i^*(t_i) = t_i$ for all i
 - Is a B-N equilibrium
 - **2** Is outcome equivalent to the equilibrium of the original (indirect) game, that is, for any $t \in T$, $M(\sigma^*(t)) = M^D(t)$
 - Proof: Define $M(\sigma^*(t)) = M^D(t)$ and note that deviations in Γ^D are equivalent to deviations to $\sigma^*_i(\hat{t}_i)$ in the game Γ . Hence IC is always true. QED
 - Powerful result, especially in implementation theory

Corollary: x is implementable whenever it is IC for the direct game.

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Static Adverse Selection: Set-Up

- Static model of optimal income taxation: Mirrlees (1971)
- Studies the efficiency-equity tradeoff shaping an optimal redistributive system
- Identical preferences over consumption $c \ge 0$ and labor $n \ge 0$

Individual welfare: U(c, n)

- Agents only differ in their productivity $heta \in [0,ar{ heta}]$
- Take labor supply decisions *n* along the intensive margin

Labor Income: $y = f(\theta, n)$

- Distribution of productivities $P(\cdot)$ is continuous
- Government unable to observe productivity or labor supply
- It only observes labor income y
- Sets an incentive compatible tax schedule to maximize social welfare *W* subject to resources feasibility

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Static Adverse Selection: Incentive Compatiblity

- Assume f is invertible and \mathcal{U} additive separable
- New preferences: $u(c) v(y, \theta)$ with income y
- Assume: $v_y(y, \theta) \ge 0$ and $v_{yy}(y, \theta) > 0$, and $v_{\theta}(y, \theta) \le 0$.
- $V(\hat{\theta}|\theta) := u(c(\hat{\theta})) v(y(\hat{\theta}), \theta)$
- IC: for all θ :

$$V(\theta) := V(\theta|\theta) \ge V(\hat{\theta}|\theta) \quad \forall \hat{\theta}$$

- FOC is $V_1(\theta|\theta) = 0$; necessary SOC: $V_{11}(\theta|\theta) \le 0$.
- By envelope FOC is equivalent to: $\dot{V}(\theta) = -v_{\theta}(y(\theta), \theta)$
- Since FOC true for all θ , by totally differentiating FOC, we get that SOC is equivalent to

$$V_{12} = -v_{\theta,y}(y(\theta),\theta)\dot{y}(\theta) \ge 0.$$

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Single Crossing

• Single-Crossing condition: If for all y and θ , $v_{\theta,y}(y,\theta) < 0$

Pictures:

$$\begin{array}{ll} \bullet & V_{12} \geq 0 \text{ (SOC) is equivalent to } \dot{y}(\theta) \geq 0 \\ \bullet & \dot{V}(\theta) = -v_{\theta}(y(\theta), \theta) \text{ and } \dot{y}(\theta) \geq 0 \text{ are also sufficient} \Rightarrow \end{array}$$

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Proof of Sufficiency

- We want to show that $\dot{y} \ge 0$ and SCC imply IC.
- Fix a generic θ and a $\hat{\theta} \neq \theta$; we have

$$V(\theta|\theta) - V(\hat{\theta}|\theta) = \int_{\hat{\theta}}^{\theta} V_1(s|\theta) ds$$

= $\int_{\hat{\theta}}^{\theta} [V_1(s|\theta) - V_1(s|s)] ds$
= $\int_{\hat{\theta}}^{\theta} \left[\int_s^{\theta} V_{12}(s|t) dt\right] ds \ge 0$

- 1. first equality by definition (assuming integrability of $V_1(\cdot|\theta)$)
- 2. second inequality holds since from FOC $V_1(s|s) \equiv 0$
- 3. third inequality is again by definition (assuming integrability)
- 4. last true because $\dot{y}(s) \ge 0$ and SCC imply:

$$V_{12}(s|t) = -v_{ heta,y}(y(s),t)\dot{y}(s) \ge 0.$$
 Q.E.D.

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Static Adverse Selection: Characterization I

- Assume: SCC and in order to get interiority $v_y(0, \theta) = 0$.
- From $V(\theta) := u(c(\theta)) v(y(\theta), \theta)$, if $g = u^{-1}$ we get

$$c(\theta) = g\left(V(\theta) + v(y(\theta), \theta)\right).$$

• Resource constraint $\int_0^{\bar{\theta}} [y(\theta) - c(\theta)] dP = 0.$

 $\max_{y(\cdot),V(\cdot)} \int_{0}^{\bar{\theta}} W(V(\theta);\theta) + \lambda \left[y(\theta) - g(V(\theta) + v(y(\theta),\theta)) \right] p(\theta) d\theta$ s.t. $\dot{V}(\theta) = -v_{\theta}(y(\theta),\theta)$ and $\dot{y}(\theta) \ge 0.$

- $\lambda > 0$ represents the cost of funds
- Welfare function. Eg, W (V(θ); θ) = ψ(θ)V(θ), then ψ(θ) represents the relative Pareto weight given to θ.

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Static Adverse Selection

Dynamic Adverse Selection

Static Adverse Selection: Characterization II

No Bunching case, i.e., if $\dot{y}(\theta) > 0$.

• Integrating by parts the Lagrangian, FOC:

$$y : p(\theta)\lambda \left[1 - \frac{v_{y}(y(\theta), \theta)}{u'(c(\theta))}\right] = \mu(\theta) \left[-v_{\theta, y}(y(\theta), \theta)\right]$$
$$V : p(\theta) \left[W'(V(\theta); \theta) - \frac{\lambda}{u'(c(\theta))}\right] = \dot{\mu}(\theta)$$

Fransv. : $\mu(0) = \mu(\bar{\theta}) = 0.$

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Static Adverse Selection: Characterization III

- 1. Recall that we have $\dot{y}(\theta) > 0$, and $\dot{V}(\theta) > 0$ (Info. Rents)
- 2. From the transversalities $\int \dot{\mu} d\theta = \mu(\bar{\theta}) \mu(0) = 0$, we have

$$\mathsf{E}\left[\frac{\lambda}{u'(c)}\right] = \mathsf{E}\left[W'(V,\cdot)\right].$$

Change $u(c(\theta))$ by ε to all agents and kip all $y(\theta)$ the same.

- 3. Recall IC: $u'(c(\theta))\dot{c}(\theta) = v_y(y(\theta), \theta)\dot{y}(\theta)$. Hence u'(c) > 0and $\dot{y}(\theta) \ge 0$ implies $\dot{c}(\theta) \ge 0$.
- 4. Claim: If W is concave and W₁₂ ≤ 0 then µ(θ) ≥ 0. Proof: Since µ(0) = 0, if µ(θ) < 0 it must be that µ(s) < 0 for s ≤ θ. From FOC w.r.t. V, using c(θ), V(θ) ≥ 0, and W₁₁, W₁₂, u'' < 0, µ(θ) decreases with θ. This implies that µ(θ') ≤ µ(θ) < 0 for all θ' ≥ θ. Contradicts µ(θ) = 0.
- 5. From [4.] and FOC w.r.t. y (SCC): $1 \frac{v_y(y(\theta), \theta)}{u'(c(\theta))} > 0$, i.e., $\tau(\theta) > 0$. Non-monotone: $\tau(0) = \tau(\bar{\theta}) = 0$.

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6. Bunching and Interpretation

Bunching: If $\dot{y}(\theta) = 0$ from IC we have $\dot{c}(\theta) = 0$.

The multiplier, i.e., the value of relaxing agent θ IC constraint: From the transversality, we have;

$$\mu(\theta) = [1 - P(\theta)]\mathbf{E}\left[\frac{\lambda}{u'(c(s))} - W'(V(s);s)|s \ge \theta\right] > 0$$

We distort agent θ 's labor supply whenever we give - on average a lower social weight $W'(V; \cdot)$ to agents with skill $s \ge \theta$ compared to their cost of funds $\frac{\lambda}{u'(c)}$ of increasing the utility to these agents. This is so since if we want to increase $y(\theta)$ we have to decrease taxes not only to agent θ we also have to increase the utility (at the margin by increasing consumption lump sum) of all agents with higher skill than him otherwise they will not tell the truth

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Variational Interpretation

• If we rewrite the FOC with the expression for $\mu(\theta)$ we have

$$p(\theta)\lambda\left[1-\frac{v_{y}(y(\theta),\theta)}{u'(c(\theta))}\right]=\mu(\theta)\left[-v_{\theta,y}(y(\theta),\theta)\right] \quad \Rightarrow$$

$$\Rightarrow \quad p(\theta)\lambda \left[1 - \frac{v_{y}(y(\theta), \theta)}{u'(c(\theta))}\right] \\ = \left[1 - P(\theta)\right] \mathbf{E} \left[\frac{\lambda}{u'(c(s))} - W'(V(s); s) | s \ge \theta\right] \left[-v_{\theta, y}(y(\theta), \theta)\right]$$

- Consider an increase in $c(\theta)$ and $y(\theta)$ such that $V(\theta)$ is constant
- A change expressed in utils (i.e., $u(c(\theta))$ changes by one unit)
- To keep IC with $\uparrow y(\theta) \dot{V}(\theta)$ must increase by $-v_{\theta,y}(y(\theta), \theta)$
- This increases U(s) for all s > θ and we can do it by increasing consumption c(s) for all s > θ while keeping y(s) constant
- The change increases u(c(s)) uniformly, hence $\uparrow c(s)$ by $\frac{1}{u'(c(s))}$

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The Taxation Principle

- In the real world, taxes are based on income, not on skill level.
- Each individual faces the same tax schedule $T : Y \to \mathbb{R}$:

$$\max_{y} y - T(y) - v\left(\frac{y}{\theta}\right)$$

Proposition For each allocation $\{(c^*(\cdot), y^*(\cdot))\}$ that solves the incentive compatibility constraints, we can construct a tax schedule $T(\cdot)$ such that any individual with skill $\theta \in \Theta$ confronted with it, optimally chooses the pair $(c^*(\theta), y^*(\theta))$. Proof. Incentive constraints become:

$$y(\theta) - T(\theta) - v\left(\frac{y(\theta)}{\theta}\right) \ge y - T(y) - v\left(\frac{y}{\theta}\right)$$
 for all y .

For all θ set $T(y^*(\theta)) = y^*(\theta) - c^*(\theta)$ and if $\nexists \theta$ such that $y = y^*(\theta)$, set $T(y) = \infty$. The taxation principle only requires the presence of a large enough punishment for incompatible choices. \Box

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Static Adverse Selection: A Formula for Taxes I

• Assume
$$f(\theta, n) = \theta n$$
; $W(V; \cdot) \equiv V$
 $\Rightarrow v(y, \theta) = v(\frac{y}{\theta}); -v_{\theta}(y, \theta) = \frac{n}{\theta}v'(n) \Rightarrow \dot{V}(\theta) = \frac{n}{\theta}v'(n).$

• The FOCs for *n* are (those for *V* are as above with $W' \equiv 1$)

$$\left(\theta - \frac{v'(n(\theta))}{u'(c(\theta))}\right)\lambda p(\theta) = \mu(\theta)\frac{v'(n(\theta)) + n(\theta)v''(n(\theta))}{\theta}$$

• From FOC of agent with net wage w we have $\frac{v'(n)}{u'(c)} = w$ and Frisch elasticity w.r.t. w

$$\varepsilon_n(\theta) := \frac{dn}{dw}_{|\bar{c}} \frac{w}{n} = \frac{u'(c)w}{v''(n)n} = \frac{v'(n)}{v''(n)}$$

• Let $c := \theta n - T(\theta n)$, from agent's FOC, the net wage equals:

$$w(\theta) := (1 - T'(y(\theta))) \theta$$

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Static Adverse Selection: A Formula for Taxes II

• Hence
$$\theta - \frac{v'(n(\theta))}{u'(c(\theta))} = T'(y(\theta))\theta$$
 and

$$\frac{v'(n(\theta)) + n(\theta)v''(n(\theta))}{\theta} = u'(c(\theta))\left(1 - T'(y(\theta))\right)\left(1 + \frac{1}{\varepsilon_n(\theta)}\right)$$

Hence FOCs become

$$T'(y(\theta))\theta p(\theta)\lambda = \mu(\theta)u'(c(\theta))\left(1 - T'(y(\theta))\right)\left(1 + \frac{1}{\varepsilon_n(\theta)}\right)$$

• Using the definition of $\mu(\theta)$ and dividing by λ , we have:

$$\frac{T'(y(\theta))}{1 - T'(y(\theta))} = \mathbf{E} \left[\frac{1}{u'(c(s))} - \frac{1}{\lambda} | s \ge \theta \right] u'(c(\theta)) \frac{1 - P(\theta)}{\theta p(\theta)} \left(1 + \frac{1}{\varepsilon_n(\theta)} \right)$$

• Note: $T' \in [0, 1)$. If $v(n) = \frac{n^{1+\frac{1}{\gamma}}}{1+\frac{1}{\gamma}}$ then $\varepsilon_n(\theta) = \gamma$ for all θ .

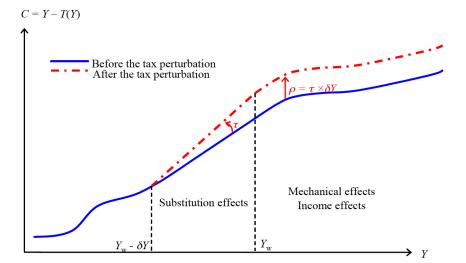


Figure 1.9: The Tax Perturbation

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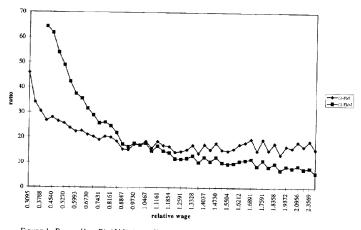


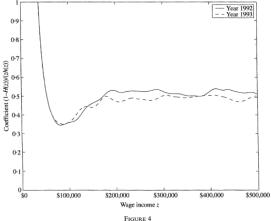
FIGURE 1. RATIOS [1 - F(n)]/f(n) and [1 - F(n)]/[nf(n)] Calculated from Relative Wages

Figure 1.10: Empirical skill distribution computed by Diamond (1998)

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Hazard ratio (1 - H(z))/(zh(z)), years 1992 and 1993

Figure 1.11: Distribution of earnings as computed by Saez (2001).

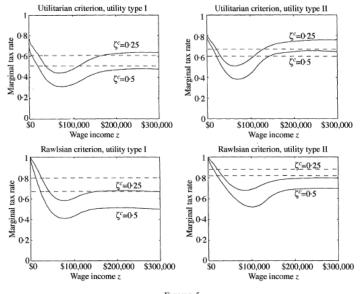


FIGURE 5 Optimal tax simulations

Figure 1.12: The numerical simulations of Saez (2001).

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The Simplest Dynamic Adverse Selection Model

 $\bullet\,$ Add payment and consumption in period zero and θ_0 known

$$\max_{c_0, y_0, y(\cdot), V(\cdot)} u(c_0) - v(y_0, \theta_0) + \beta \int_0^{\bar{\theta}} V(\theta) p(\theta) d\theta$$
$$+ \lambda \left[y_0 - c_0 + q \int_0^{\bar{\theta}} \left[y(\theta) - g \left(V(\theta) + v(y(\theta), \theta) \right) \right] p(\theta) d\theta \right]$$
s.t. $\dot{V}(\theta) = -v_{\theta}(y(\theta), \theta)$ and $\dot{y}(\theta) \ge 0.$

- q = price of the bond and $\beta =$ agent's discount factor.
- θ only revealed to the agent at t = 1. Full Commitment
- Obviously, y_0 such that $1 = \frac{v_y(y_0,\theta_0)}{u'(c_0)}$.
- Euler variation: $\frac{\beta}{u'(c_0)} = \frac{1}{\lambda} = \mathbf{E} \left[\frac{q}{u'(c)} \right].$
- Using Jensen's Inequality (positive capital tax?):

 $qu'(c_0) < \mathbf{E} \left[\beta u'(c)
ight].$

Intuitions for the Previous Result

- Bond is a bad asset for incentives as it increases utility in an unbalanced way, detrimental for incentives
- Ø Joint deviations
- Frontloaded consumption desirable: Since c₁ > 0 when qu'(c₀) = βE [u'(c₁(θ))] the planner can increase c₀ and reduce all c₁(θ) keeping IC. If the agent is contemplating to lie, s/he will reduce next period expected returns and consumption. As a consequence he would like a relatively low c₀. To discourage this deviation the planner keeps c₀ relatively high at the expenses of future payments.
- Social intertemporal margin differs form the private: A bond perturbation $\downarrow c_0$ by $\beta \epsilon$ and $\uparrow c_1(\theta)$ by ϵ makes lying more attractive, hence it induces an additional cost for the planner.

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Implementation Results

- Golosov and Tsyvinski (2006): DI with absorbing shocks
 - Means tested transfers on income: Upperbound on wealth or \boldsymbol{k}
- Albanesi and Sleet (2006): iid shocks
 - One-to-one mapping between k(heta) and U(heta), with $\dot{y}(heta) \geq 0$
 - $\tau(k, y)$ with $\tau_{y,k}(k, y) \neq 0$
- Kocherlakota (2005): general income process

$$1 - \tau^k(\theta) := \frac{qu'(c_0)}{\beta u'(c(\theta))}$$

hence, by construction zero expected tax on capital:

$$\mathbf{E}\left[\left(1-\tau^{k}(\theta)\right)\right]=1 \quad \Rightarrow \mathbf{E}\left[\tau^{k}(\theta)\right]=0.$$

- Pavoni and Violante (2005): UI discrete effort Tax for joint deviations and leave all agents at their liquidity constraint, say k ≥ 0. Positive capital income tax
- Gottardi Pavoni (2011): Moral Hazard Uncontingent tax ⇒ optimal tax on bond price is positive

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The Value of Enduring Relationships I

- Pioneers: Townsend (1982), Green (1987), and Thomas and Worrall (1991)
- Endowment Economy
 - The model can be sees as a special case of our Mirrlees

•
$$\mathcal{U}(c, n) = u(c - n)$$
 and $y = f(\theta, n) = \theta + n$

•
$$U(\theta) := u(c(\theta) - y(\theta) + \theta) = u(\tau(\theta) + \theta)$$

- Only relevant the insurance aspect: $\tau(\theta):=y(\theta)-c(\theta)$
- Start with the Static Model

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Dynamic Model: Heuristic Intro to Recursive Constracts Define first of all, the following value function

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$$V(w) := \max_{\tau(\cdot)} -\int_{0}^{\theta} \tau(\theta)p(\theta)d\theta$$

s.t. for all θ , $\hat{\theta}$
 $u(\tau(\theta) + \theta) \ge u(\tau(\hat{\theta}) + \theta);$ $(IC_{\theta,\hat{\theta}})$
 $w = \int_{0}^{\bar{\theta}} u(\tau(\theta) + \theta)p(\theta)d\theta.$ (PK)

• The IC implies $\dot{\tau}(\theta) = 0$ so no insurance

$$u(\tau(\theta) + \theta) \ge u(\tau(\hat{\theta}) + \theta)$$

$$\Rightarrow \text{ FOC } u'(\tau + \theta)\dot{\tau}(\theta) = 0 \Rightarrow \text{Autarchy!}$$

• Envelope: $V'(w) = \frac{1}{\int_0^{\theta} u'(\tau(\theta) + \theta)p(\theta)d\theta}$

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Dynamic Model: Heuristic Intro to Recursive Contracts

- Consider the two period repetition
- In t = 1 first shock θ ; in t = 2 second shock θ'
- Planner Problem

$$\max_{\tau_{1}(\cdot),w(\cdot)} \int_{0}^{\bar{\theta}} \left[-\tau_{1}(\theta) + qV(w(\theta)) \right] p(\theta) d\theta$$

s.t.
$$\int_{0}^{\bar{\theta}} \left[u(\tau_{1}(\theta) + \theta) + \beta w(\theta) \right] p(\theta) d\theta \ge U_{0}; \qquad (IR)$$
$$u(\tau_{1}(\theta) + \theta) + \beta w(\theta) \ge u(\tau_{1}(\hat{\theta}) + \theta) + \beta w(\hat{\theta}). \qquad (IC)$$

- What matters for the IC and IR is the promized utility w
- IC uses $\tau_1(\theta)$ and $w(\theta) \iff \tau_2(\theta, \theta')$
- From previous argument, $\tau_2(\theta, \theta') \equiv \tau_2(\theta)$.

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Recursive contracts: Formal Derivation

Sequential Problem

$$\max_{\substack{\tau_{1}(\theta),\tau_{2}(\theta,\theta')}} \int_{0}^{\bar{\theta}} \left[-\tau_{1}(\theta) + q \int_{0}^{\bar{\theta}} -\tau_{2}(\theta,\theta')p(\theta')d\theta' \right] p(\theta)d\theta \quad \text{s.t.}$$

$$\int_{0}^{\bar{\theta}} \left[u(\tau_{1}(\theta) + \theta) + \beta \left(\int_{0}^{\bar{\theta}} u\left(\theta' + \tau_{2}(\theta,\theta')\right)p(\theta')d\theta' \right) \right] p(\theta)d\theta \ge U_{0}; \ (IR)$$

$$u(\tau_{1}(\theta) + \theta) + \beta \int_{0}^{\bar{\theta}} u\left(\theta' + \tau_{2}(\theta,\theta')\right)p(\theta')d\theta' \qquad (IC)$$

$$\ge u(\tau_{1}(\hat{\theta}) + \theta) + \beta \int_{0}^{\bar{\theta}} u\left(\theta' + \tau_{2}(\hat{\theta},\theta')\right)p(\theta')d\theta' \forall \hat{\theta} \in \Theta$$

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Step 1: useful redefinition

The transfer scheme (contract) can be written as $\mathcal{T} := \{\tau_1(\theta), \mathcal{T}_2(\theta)\}_{\theta \in \Theta}, \text{ where } \forall \theta \ \mathcal{T}_2(\theta) := \{\tau_2(\theta, \theta')\}_{\theta' \in \Theta}$ Let

$$\mathbf{V}(\mathcal{T}_2(heta)) := \int_0^ heta - au_2(heta, heta') p(heta') d heta'$$

be the planner value in period 2 from contract after $\boldsymbol{\theta}$ occurred in period 1.

Similarly, for the agent, the equilibrium expected value

$$\mathbf{U}(\mathcal{T}_{2}(\theta)) := \int_{0}^{\bar{\theta}} u\left(\theta' + \tau_{2}(\theta, \theta')\right) p(\theta') d\theta'.$$

Note, these are values from any contract

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Planner's Problem

Then planner problem can be written as

$$\begin{split} \max_{\tau_1(\cdot),\mathcal{T}_2(\cdot)} & \int_0^{\bar{\theta}} \left[-\tau_1(\theta) + q \mathbf{V}(\mathcal{T}_2(\theta)) \right] p(\theta) d\theta \\ \text{s.t.} & \int_0^{\bar{\theta}} \left[u(\tau_1(\theta) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\theta)) \right] p(\theta) d\theta \geq U_0; \end{split}$$

 $\forall \theta \in \Theta: \quad u(\tau_1(\theta) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\theta)) \ge u(\tau_1(\hat{\theta}) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\hat{\theta})) \quad \forall \hat{\theta}$

 $\forall (\theta, \theta') \in \Theta^2: \quad u(\theta' + \tau_2(\theta, \theta')) \geq u(\theta' + \tau_2(\theta, \hat{\theta}')) \ \forall \hat{\theta}' \in \Theta$

NB: Since shocks are iid from the last IC, any agent who lied in period one still has incentive to tell the truth in period 2.

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Step 2: A New Variable

Now, for each \mathcal{T} let, for each $\theta \in \Theta$ $w(\theta) := U(\mathcal{T}_2(\theta))$. The above problem is equivalent to

$$\begin{split} \max_{\tau_1(\cdot), \mathbf{w}(\theta), \mathcal{T}_2(\cdot)} & \int_0^{\bar{\theta}} \left[-\tau_1(\theta) + q \mathbf{V}(\mathcal{T}_2(\theta)) \right] p(\theta) d\theta \\ \text{s.t.} & \int_0^{\bar{\theta}} \left[u(\tau_1(\theta) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\theta)) \right] p(\theta) d\theta \geq U_0; \end{split}$$

 $\forall \theta \in \Theta: \quad u(\tau_1(\theta) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\theta)) \ge u(\tau_1(\hat{\theta}) + \theta) + \beta \mathbf{U}(\mathcal{T}_2(\hat{\theta})) \ \forall \hat{\theta}$

$$\forall (\theta, \theta') \in \Theta^2: \qquad \quad u(\theta' + \tau_2(\theta, \theta')) \geq u(\theta' + \tau_2(\theta, \hat{\theta}')) \ \ \forall \hat{\theta}' \in \Theta$$

 $\forall \theta \in \Theta: \quad w(\theta) = \mathbf{U}(\mathcal{T}_2(\theta))$

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Step 3: The Bellman Principle

- We are now able to give a form to the value $\mathbf{V}(\mathcal{T}_2(heta))$
- Notice that when w(θ) is chosen, T₂(·) does not affect period zero choices of τ₁(·).
 We can hence 'pass the max over'

$$\max_{\tau_{1}(\cdot),\boldsymbol{w}(\theta)} \int_{0}^{\tilde{\theta}} \left[-\tau_{1}(\theta) + q \max_{\substack{\mathcal{T}_{2}(\theta)s.t.\\\boldsymbol{w}(\theta) = \mathbf{U}(\mathcal{T}_{2}(\theta))\\\boldsymbol{u}(\theta' + \tau_{2}(\theta,\theta')) \geq \boldsymbol{u}(\theta' + \tau_{2}(\theta,\hat{\theta}')) \forall \hat{\theta}'} \\ \text{s.t.} \quad \int_{0}^{\tilde{\theta}} \left[\boldsymbol{u}(\tau_{1}(\theta) + \theta) + \beta \boldsymbol{w}(\theta) \right] \boldsymbol{p}(\theta) d\theta \geq U_{0}; \end{cases} \right]$$

 $\forall \theta \in \Theta: \quad u(\tau_1(\theta) + \theta) + \beta w(\theta) \ge u(\tau_1(\hat{\theta}) + \theta) + \beta w(\hat{\theta}) \ \forall \hat{\theta} \in \Theta.$

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The 'handy' recursive formulation

$$V_{1}(w_{0}) = \max_{\tau_{1},w} \int_{0}^{\bar{\theta}} \left[-\tau_{1}(\theta) + qV(w(\theta)) \right] p(\theta)d\theta$$

s.t.
$$\int_{0}^{\bar{\theta}} \left[u(\tau_{1}(\theta) + \theta) + \beta w(\theta) \right] p(\theta)d\theta = w_{0}; \quad (\mathsf{PK})$$
$$\forall \theta \in \Theta: \quad u(\tau_{1}(\theta) + \theta) + \beta w(\theta) \ge u(\tau_{1}(\hat{\theta}) + \theta) + \beta w(\hat{\theta}) \quad \forall \hat{\theta} \in \Theta.$$

 MULTIPERIOD: In the recursive formulation, for a given level of promised utility w_t the government chooses a transfer scheme and promises for future utility w_{t+1}(θ), and so on.

• The constraint (PK) is the 'promise-keeping' constraint that requires the contract to deliver the promised level of utility. It plays the role of a law of motion for the state variable w_0 .

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Observations

- Note the we have an equality above. One must be careful in distinguishing between 'utility possibility frontier' and 'Pareto frontier'
- Because of the Bellman Principle, all that matters to reconstruct the optimal contract continuation is a particular 'statistic' $w(\theta) = \mathbf{U}(\mathcal{T}_2^*(\theta))$, one number for each θ in this case.
- This number induces a constraint on the next period problem. We then let the planner 're-maximize' subject to this constraint.
- Optimality requires that $\mathbf{V}(\mathcal{T}_2^*(\theta)) = V(w(\theta))$. That is, the planner always goes on the frontier of the utility possibility set.

Notions of Mechanism Design

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The Optimal Allocation I

• The Relaxed planner's problem

$$\max_{\tau_{1},w} \int_{0}^{\bar{\theta}} \left[-\tau_{1}(\theta) + qV(w(\theta)) \right] p(\theta)d\theta$$

s.t.
$$\int_{0}^{\bar{\theta}} \left[u(\tau_{1}(\theta) + \theta) + \beta w(\theta) \right] p(\theta)d\theta \ge U_{0}; \qquad (IR)$$

$$\dot{\tau}_{1}(\theta)u'(\tau_{1}(\theta) + \theta) + \dot{w}(\theta) = 0. \qquad (IC)$$

It can be shown that

$$\dot{w}(\theta) = \dot{\tau}_2(\theta) \mathbf{E} \left[u'(\tau_2(\theta) + \theta')
ight]$$

Notions of Mechanism Design

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The Optimal Allocation II

- From IC we immediately have: if $\dot{\tau}_1(\theta) < 0$ then $\dot{\tau}_2(\theta) > 0$
- Intuition: Recall the intertemporal utility of agent $\theta_1 = \theta$:

$$u(\tau^{1}(\theta) + \theta) + \beta \mathbf{E}u(\tau^{2}(\theta) + \theta').$$

In t = 1 low θ 's expect an improvement of the situation, hence willing to give up on the future for a today's subsidy $\tau_1 > 0$. High θ 's expect a deterioration hence are willing to accept $\tau_1 < 0$ for a deterministic increase in future payments $\tau_2 > 0$.

• Endogenous return to savings

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The Optimal Allocation III

• If we integrate by parts in the Lagrangian:

$$\int \mu(\theta)\dot{\tau}_{2}(\theta)\mathbf{E}\left[u'(\tau_{2}(\theta)+\theta')\right]d\theta = \int \dot{\mu}(\theta)\mathbf{E}\left[u(\tau_{2}(\theta)+\theta')\right]$$

and
$$\int \mu(\theta)\dot{\tau}_{1}(\theta)u'(\tau_{1}(\theta)+\theta)d\theta$$
$$= \int \mu(\theta)\left[1+\dot{\tau}_{1}(\theta)\right]u'(\tau_{1}(\theta)+\theta)d\theta - \int \mu(\theta)u'(\tau_{1}(\theta)+\theta)d\theta$$
$$= \int \dot{\mu}(\theta)u(\tau_{1}(\theta)+\theta)d\theta - \int \mu(\theta)u'(\tau_{1}(\theta)+\theta)d\theta$$

• The associated Lagrangian becomes:

$$\mathcal{L} = \int_{0}^{\bar{\theta}} \left[-\tau_{1}(\theta) - q\tau_{2}(\theta) \right] p(\theta) d\theta - \int \mu(\theta) u'(\tau_{1}(\theta) + \theta) d\theta + \int_{0}^{\bar{\theta}} \left[\lambda p(\theta) + \dot{\mu}(\theta) \right] \left\{ u(\tau_{1}(\theta) + \theta) + \beta \mathbf{E} \left[u(\tau_{2}(\theta) + \theta') \right] \right\} d\theta$$

Notions of Mechanism Design

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The Optimal Allocation IV

• The FOCs :

$$\begin{bmatrix} \frac{1}{u'(\tau_1(\theta) + \theta)} - \lambda \end{bmatrix} p(\theta) = \dot{\mu}(\theta) - \mu(\theta) \frac{u''(\tau_1(\theta) + \theta)}{u'(\tau_1(\theta) + \theta)}$$
$$\begin{bmatrix} \frac{q}{\beta \mathbf{E} \left[u'(\tau_2(\theta) + \theta') \right]} - \lambda \end{bmatrix} p(\theta) = \dot{\mu}(\theta)$$

• Rearranging terms and using IC we have

$$\rho(\theta)\frac{\dot{\tau}_1(\theta) + q\dot{\tau}_2(\theta)}{\dot{\tau}_1(\theta)u'(\tau_1(\theta) + \theta)} = \mu(\theta)a(\theta) > 0,$$

where
$$a(heta) = -rac{u''(au_1(heta)+ heta)}{u'(au_1(heta)+ heta)}$$

• Since $\dot{\tau}_1(\theta) < 0$ it must be that (NPV decreases with θ)

$$\dot{\tau}_1(\theta) + q\dot{\tau}_2(\theta) < 0.$$

Notions of Mechanism Design

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Endogenizing Market Incompleteness

• Consider again the IC

$$\dot{\tau}_1(\theta) + \dot{\tau}_2(\theta)\beta \int_0^{\bar{\theta}} \frac{u'(c_2(\theta, \theta'))}{u'(c_1(\theta))} p(\theta') d\theta' = 0$$

- Assume now the agent has access to credit market as the planner
- Bond price = q
- Standard EEq.: Let $c_t = au_t + heta_t$

$$eta \int_0^{ar{ heta}} rac{u'(c_2(heta, heta'))}{u'(c_1(heta))} p(heta') d heta' = q \quad orall heta$$

 $\Rightarrow \dot{\tau}_1(\theta) + q\dot{\tau}_2 = 0$

- The planner can only mimic the bond, no insurance on top of self-insurance: Bond economy
- Informational frictions can be used to explain why insurance markets are incomplete
- \Rightarrow Macro Literature on Endogenous incomplete markets

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Dynamic Adverse Selection and Commitment

- Full Commitment and no skill shocks: Identical to the static model (with randomizations)
- **2** No Commitment: Neither the principal nor the agent can commit after θ) is realized and it has been announced.
 - Take the Money and run
 - Ratchet effect
 - \Rightarrow with continuum of types the contract is pooling
- Partial commitment
 - Only commitment on the planner: Ex-post incentives (Rawlsian)
 - Only commitment on the agent: Restricted Revelation principle (Bester and Strausz, Econometrica, 2001)
 - Many agents vs 1 agent
 - Incentive feasible versus Constrained Efficient
 - True-telling with P > 0 (random mechanisms)