FISCAL POLICY IN GOOD TIMES AND BAD*

Roberto Perotti Columbia University and CEPR

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Abstract

In the eighties, several countries with large government debt or deficit implemented substantial, and in some cases drastic, deficit cuts. Contrary to widespread expectations, in many cases private consumption boomed rather than contract. This paper shows that in times of "fiscal stress" shocks to government revenues and, especially, expenditure have very different effects on private consumption than in "normal" times.

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1 Introduction.

In the eighties, several countries embarked in substantial, and sometimes drastic, fiscal consolidations after years of accumulation of government debt. The response of the economy to these contractionary fiscal policies often surprised economists and policymakers alike.

In a seminal contribution, Giavazzi and Pagano [1990] studied the two largest fiscal consolidations of the eighties - Denmark in 1983-86 and Ireland in 1987-89. During these episodes, the cyclically adjusted deficit fell by a startling 9.5 percent and 7.2 percent of GDP relative to the pre-consolidation year, respectively, and yet private consumption increased by 17.7 percent and 14.5 percent cumulatively. Alesina and Perotti [1996] identify 7 episodes of prolonged and substantial consolidations: the two episodes above, plus Belgium 1984-87, Canada 1986-88, Italy 1989-92, Portugal 1984-86, Sweden 1983-89. In each of these episodes, the primary deficit in the two years after the adjustment was smaller than the average before the adjustment by at least 5 percent of GDP, except in Canada, where the difference is 4.4 percent of GDP. Yet, in all these cases the rate of growth of private consumption was positive in every single year, and it always exceeded the pre-adjustment average rate of growth, with the exception of the Italian episode.¹ It is by now common to refer to this type of episodes as 'expansionary fiscal consolidations'.

Of course, life is not always this easy. Most of the time, we would expect fiscal consolidations to have a cost, which is exactly why they are so difficult to come about. One common aspect of the consolidations cited above is that they all occurred at exceptionally high levels of the debt/GDP ratio (as in Belgium, Italy, and Ireland) or immediately following exceptionally high rates of accumulation of debt (in the other countries). While *per se* this fact is hardly surprising, it does suggest the interesting possibility that in times of fiscal stress the economy's response to fiscal shocks changes qualitatively.

The purpose of this paper is precisely to investigate on a yearly panel of 19 OECD countries whether the effects of fiscal policy depend on the initial conditions. As a guide to the empirical investigation, I first lay out a simple model where government expenditure shocks have a positive, "keyne-

¹These numbers are all the more remarkable because the episodes are identified on the basis of the behavior of the cyclically-adjusted deficit, and therefore they are unlikely to be an artifact of cyclical variations in consumption and growth.

sian" correlation with private consumption in normal times, and a negative, "non-keynesian" correlation in bad times. Symmetrically, tax shocks have a negative, "keynesian" correlation in normal times and a positive, "nonkeynesian" correlation in bad times. It is important to emphasize that what is needed to rationalize the type of episodes described above is a model in which the correlation between private consumption and shocks to government expenditure and revenues *changes*, depending on the initial conditions. For instance, in a standard neoclassical model a cut in government consumption would always have expansionary effects on private consumption: when government consumption falls, private wealth increases, and so does private consumption. However, such a model would not in itself display a *switch* in the effects of fiscal policy, and neither would a purely keynesian model.

Although on the tax side it is based on a similar logic to Blanchard [1990] and Sutherland [1997], the model presented here is still useful because it develops a coherent framework where the effects of *both* tax *and* expenditure shocks can be analyzed. This is particularly important because, empirically, there seems to be more support for a switch in the effects of the latter than the former. Bertola and Drazen [1993] also model the effects of government consumption as a function of its initial level. As discussed in section VIII, the implications they derive are very different from those developed here. The present model also avoids the large discontinuities in the behavior of policymakers and in the public's expectations that are typically assumed in the existing models of expansionary fiscal consolidations.

The empirical part of the present paper provides considerable support for the notion that initial conditions matter for the effects of fiscal shocks, in particular of government expenditure. It belongs to a rapidly growing body of research on the composition and effects of fiscal consolidations. Aside from the paper by Giavazzi and Pagano [1990] mentioned above, Alesina and Perotti [1995, 1997a] and Alesina and Ardagna [1998] show that different types of consolidations have very different degrees of persistence and of correlations with macroeconomic variables. Coeur et al. [1996], De Menil [1996], Heylen [1997], IMF [1996], and OECD [1996] also perform thorough empirical analyses of the properties and effects of fiscal consolidations, largely confirming but also qualifying along various dimensions the results of Alesina and Perotti.

The closest antecedent of this paper is Giavazzi and Pagano [1996]. These authors also study the response of private consumption to fiscal policy on a yearly panel of OECD countries. Their main focus is on the relationship between consumption and the size and persistence of fiscal policy changes, rather than on the role of initial conditions. They also use a different econometric methodology, which is difficult to map into the theoretical framework used here.

The plan of the paper is as follows. The next section sets up the model, and section III develops its solution. Section IV studies the effects of expenditurebased and tax-based consolidations in this model. Section V discusses estimation issues, while section VI discusses the data and some preliminary empirical issues. Section VII presents the empirical results. Section VIII concludes by discussing the related literature and some open remaining issues.

2 The model.

The model has four key ingredients, each of them fairly standard in macroeconomic models: first, distortionary taxation; second, a policymaker who effectively discounts the future more than the private sector, so that the economy is initially away from a position of perfect tax-smoothing; third, the coexistence of credit constrained individuals and individuals with free access to credit markets; fourth, government expenditure has a positive effect on output.

Whenever at least some individuals have access to credit markets, fiscal policy shocks generate wealth effects from anticipated future responses of fiscal policy, via the intertemporal government budget constraint. To incorporate these effects, I consider a simple model where consumers live for 3 periods (denoted by 0, 1, and 2, respectively) and I study the change in consumption between period 1 and 0 as a function of the fiscal policy shocks in period 1. The future response of fiscal policy to the current shock is then summarized by the behavior of fiscal policy in period 2, the last period of the model. This setup contains all the essential features of the analysis.

Individuals have quadratic utility,² and their only decision concerns the

²Without this assumption, it would be impossible to obtain a closed form solution for the consumer's problem, since the first order conditions would involve higher moments of consumption than the first. In the specific case of the model, the problem would be compounded by the fact that, as shown below, the budget constraint of the consumer is non-linear in taxes, which are stochastic. However, note that precautionary savings would *reinforce* the main conclusion of the model. When a fiscal consolidation occurs, uncertainty on how the government's intertemporal budget constraint will be satisfied

choice between consumption and savings. The population is divided into two types of individuals: a mass $1 - \mu$ have unrestricted access to credit markets at the market interest rate, while the remaining fraction μ are credit constrained. Thus, the pervasiveness of credit constraints in the economy is indexed by μ .

From standard consumption smoothing arguments, and assuming for simplicity that both the rate of time preference and the interest rate are 0, the change in consumption of unconstrained individuals between periods 1 and 0 is simply half the innovation in the PDV of their disposable income

(1)
$$\Delta C_1^u = \frac{1-\mu}{2} \left[(Y_1 - Y_{1/0}) + (Y_{2/1} - Y_{2/0}) \right] + \epsilon_1$$

where the superscript 'u' refers to 'unconstrained' individuals, Y_i represents disposable income in *i*, and $X_{i/j}$ denotes the expectation of X in period *i*, formed in period *j*. The disturbance ϵ_1 represents, for instance, transitional consumption and in general shocks to preferences in period 1. Its properties will be important when discussing the estimation of the model, but for the purposes of the present section it is useful to think of the simple case of an i.i.d. shock.

Following Hayashi [1982], Campbell and Mankiw [1989] and [1990], and many others, credit constraints have a very simple but convenient form: constrained individuals cannot borrow or lend, therefore they consume all their disposable income in each period. Hence, for such individuals the change in consumption between periods 1 and 0 is identically equal to the change in disposable income:

(2)
$$\Delta C_1^c = \mu \Delta Y_1$$

where the superscript 'c' refers to 'unconstrained' individuals.

To solve for the change in aggregate consumption one only needs to specify a process for disposable income. A sufficiently general form is:

(3)
$$Y_t = \overline{Y} + Z_t \alpha + \beta G_t - T_t - \lambda T_t^2 + \zeta_t^Y, \quad \beta > 0; \quad \lambda > 0$$

falls. If this uncertainty is larger at larger levels of debt (as it is seems natural to assume) a consolidation has larger positive effects on consumption the larger the initial level of debt.

where Z_t is a row vector of variables and α a column vector of associated coefficients, T_t is total taxes on individuals, ζ_t^Y is a stochastic disturbance, and G_t is government expenditure. In the empirical section, I will consider the various components of government expenditure - the wage and the non-wage components of current spending on goods and services, the capital component of spending on goods and services, and transfers - separately. Until then, I will use the generic term "government expenditure" when referring to the variable G_t .

Let ϵ_t^X denote the innovation of the variable X on the basis of the information at time t-1: $\epsilon_t^X = X_t - E(X_t/\Omega_{t-1})$. Z_t follows the law of motion:

(4)
$$Z_t = \bar{Z} + Z_{t-1}\rho + \epsilon_t^Z$$

The specific form of the vector Z_t will be important only when discussing the econometric methodology. Hence, to simplify the notation from now I will assume that Z_t is a scalar and I will concentrate on the role of the fiscal policy variables.

From expression (3), taxes have two types of effects on disposable income. The first is obvious: an increase in taxation causes a one-to-one fall in the after-tax disposable income. According to this effect, only the PDV of taxation, not its timing, would matter to unconstrained individuals if taxation were non-distortionary. The second effect of taxation is the distortions it causes on pre-tax income; in this model with inelastic labor supply and no investment, this effect is captured in a very simple way by the quadratic term $-\lambda T_t^{2.3}$

If the initial expected path of taxation is upward sloping (i.e., $T_{1/0} < T_{2/0}$), a consolidation in period 1 that increases current taxes at a given PDV of taxation causes T_1 to get closer to $T_{2/1}$. As a consequence, the PDV of tax distortions falls and the wealth of unconstrained individuals increases. Hence, an upward-sloping expected path for taxation is a necessary condition for a

³It is usually assumed that distortions are a function of the square of the tax *rate*, rather than of total tax revenues like here. This would make the model intractable analytically, because it would require computing the variance of a term like T_t/Y_t , where both the numerator and the denominator are stochastic and, moreover, the denominator is a function of the numerator. The formalization adopted here simplifies the exposition without sacrificing anything substantive. Note also that this is the specification adopted for instance by Sargent [1987].

rise in taxes to be associated with an increase in consumption.⁴ In this model there are two natural and very compelling reasons for an upward sloping expected path of taxation. First, even if taxes were set by a benevolent dictator with the same horizon as the whole economy, a tax-smoothing policy would not maximize the expected lifetime utility of constrained individuals: if pre-tax disposable income is increasing over time, their expected lifetime utility would be maximized if taxes also were growing over time, so as to smooth disposable income and therefore consumption. Second, an upward sloping expected path for taxation is the natural outcome of virtually any realistic positive description of tax policy in this model. In particular, this would be the outcome if the tax rate were set in each period by a policymaker with a shorter effective horizon than the economy, for instance because the probability of re-election is smaller than 1, as in Tabellini and Alesina [1990]. In fact, it is easy to show that in the present model one would obtain $T_{1/0} =$ $pT_{2/0}$, where p is the probability of re-election. From now on, this is the assumption I will make on the relationship between the expected taxes in the two periods.⁵

Still in expression (3), government expenditure has a positive impact on the disposable income of the private sector. While this is obvious in the case of transfers, in the case of spending on goods and services it would be true in any model where aggregate demand has an effect on output. Here I simply assume this effect without modeling it explicitly.

Government expenditure is $exogenous^6$, and obeys the simple process:

(5)
$$G_t = \bar{G} + \theta_0 G_{t-1} + \epsilon_t^G$$

Given the expected path of expenditure, the expected path of taxation must

⁴This is the basic intuition of Blanchard [1990] and Sutherland [1997]; in those models, the expectation of high future taxation is conditional on the government debt to GDP ratio reaching the maximum "acceptable" level of debt \bar{b} . Thus, the reasons for the absence of tax-smoothing are very different from the present model. As a consequence, the present model does not require the large discontinuity in the behavior of policymakers at \bar{b} , nor in the expectations of the private sector.

⁵For simplicity, I will also assume that p is constant.

⁶Expenditure could be easily endogenized, using a framework similar to Tabellini and Alesina [1990]. For the purposes of the present investigation, however, an exogenous government expenditure will suffice. obey the intertemporal budget constraint, which from the perspective of time t states:

(6)
$$\Sigma_{i=t+1}^2 T_{i/t} = \Sigma_{i=t+1}^2 G_{i/t} + B_t; \quad t = 0, 1; \quad B_2 = 0$$

where B_t is the stock of government debt at the end of period t, which is known in period t.⁷ The r.h.s. of (6) can be interpreted as the PDV of the financing needs of the government. For brevity, I will indicate it with L_t . Expressions (5) and (6) provide the link between current shocks and future changes in fiscal policy.

3 Solution.

This section solves for the change in aggregate consumption in period 1, ΔC_1 , as a function of the tax and expenditure shocks, ϵ_1^G and ϵ_1^T . Consider first the change in consumption of unconstrained individuals, ΔC_1^u . From (3), and using a first-order Taylor expansion of T_1^2 around $T_{1/0}$ to linearize the term $(T_1^2 - E_{1/0}(T_1^2)), Y_1 - Y_{1/0}$ in expression (1) can be written as:

(7)
$$Y_1 - Y_{1/0} = \alpha \epsilon_1^Z + \beta \epsilon_1^G - (1 + 2\lambda T_{1/0})\epsilon_1^T + \zeta_t^Y$$

Similarly, the term $Y_{2/1} - Y_{2/0}$ in (1) can be expressed as:

(8)

$$Y_{2/1} - Y_{2/0} = \alpha \rho \epsilon_1^Z + \beta (G_{2/1} - G_{2/0}) - (T_{2/1} - T_{2/0}) - \lambda \left[E_{2/1}(T_2^2) - E_{2/0}(T_2^2) \right]$$

Using the law of motion for G_t (equation (5)), the intertemporal government budget constraint (expression (6)), and after linearizing T_2^2 around $T_{2/0}$, one finally obtains:

(9)
$$\Delta C_1^u = \gamma_1^u \epsilon_1^G + \gamma_2^u \epsilon_1^T + \eta_1^u$$

⁷Note that, in order to simplify the notation, I assume that the spending variables appearing in (5) and in (6) are the same. This need not be so in the empirical part: while G_t in (5) is total government spending, in (6) it is the particular type of government expenditure being investigated.

where

(10)
$$\gamma_{1}^{u} = (1-\mu)\frac{(1+\theta_{0})}{2} \left[\beta - (1+2\lambda T_{2/0})\right]$$
$$\gamma_{2}^{u} = (1-\mu)\lambda \left[T_{2/0} - T_{1/0}\right] > 0$$
$$\eta_{1}^{u} = (1-\mu)\frac{1}{2} \left[\alpha(1+\rho)\epsilon_{1}^{Z} + \zeta_{1}^{Y}\right] + (1-\mu)\epsilon_{1}$$

Thus, γ_1^u and γ_2^u capture the effects of expenditure and tax shocks on the consumption of unconstrained individuals. Their interpretation is straightforward. Starting with γ_1^u , a unitary expenditure shock in period 1 causes the expected PDV of government consumption to increase by $(1 + \theta_0)$. This increases the expected PDV of income by $\beta(1 + \theta_0)$. However, the expected PDV of taxation also increases by $(1 + \theta_0)$ by the intertemporal government budget constraint, causing a total of approximately $(1 + \theta_0)2\lambda T_{2/0}$ extra tax distortions. Half of the total net effect of the shock on the expected PDV of income is consumed.

The expression for γ_2^u is equally intuitive. Holding constant government expenditure, an increase in taxation in period 1 must be exactly offset by an equal fall in taxation in period 2. The expected PDV of taxation does not change, but distortions in period 1 increase by approximately $2\lambda T_{1/0}$, while in period 2 they fall by approximately $2\lambda T_{2/0}$. The overall change in the expected PDV of income is therefore $2\lambda(T_{2/0} - T_{1/0})$, half of which is consumed in period 1. All other shocks are collapsed into the error term η_1^u .

Turning to constrained individuals, from (2) the change in their consumption is equal to the change in their disposable income. The latter can be expressed as the sum of the unexpected and of the expected (as of time 0) changes, and using (3) this gives

(11)
$$\Delta C_1^c = \gamma_1^c \epsilon_1^G + \gamma_2^c \epsilon_1^T + \eta_1^c + \mu (Y_{1/0} - Y_0)$$

where the first three terms on the r.h.s. represent the unexpected change, the last term is the expected change, and

(12)
$$\gamma_1^c = \mu\beta > 0; \quad \gamma_2^c = -\mu(1 + 2\lambda T_{1/0}) < 0; \quad \eta_1^c = \mu(\alpha\epsilon_1^Z + \zeta_1^Y)$$

For constrained individuals, there is no wealth effect from future anticipated changes in fiscal policy. Hence, holding constant current taxation, the effect of an expenditure shock, γ_1^c , is just its positive current effect, β , multiplied by the share of constrained individuals, μ . This effect is unambiguously positive, and also independent of the initial conditions. Holding constant current expenditure, the effect of a tax shock, γ_2^c , is just its contemporaneous effect on disposable income, including the extra distortions it causes: once linearized, this effect is equal to $-(1 + 2\lambda T_{1/0})$, multiplied by the share of constrained individuals, μ . Hence, it is unambiguously negative. Combining (9) and (11) one obtains an explicit expression for the change in aggregate consumption as a function of fiscal policy shocks:

(13)
$$\Delta C_1 = \gamma_1 \epsilon_1^G + \gamma_2 \epsilon_1^T + \mu (Y_{1/0} - Y_0) + \eta_1$$

where

(14)
$$\gamma_1 = \gamma_1^u + \gamma_1^c; \quad \gamma_2 = \gamma_2^u + \gamma_2^c; \quad \eta_1 = \eta_1^u + \eta_1^c$$

Thus, γ_1 and γ_2 capture the effects of expenditure and tax shocks on the consumption of both unconstrained and constrained individuals. Expression (13) is the basis for the analysis of the effects of expenditure- and tax- based consolidations.

4 The effects of expenditure and revenue shocks.

The basic strategy is to investigate the signs of the two coefficients γ_1 and γ_2 in equation (14) as functions of the parameters of the model. In particular, I will focus on L_0 , the PDV of the financing needs of the government from the perspective of time 0, p, the probability of reelection, and μ , capturing the pervasiveness of credit constraints in the economy. The first two parameters determine the values of $T_{2/0}$, $T_{1/0}$, and $T_{2/0} - T_{1/0}$, which in turn determine the values of the initial distortions appearing in (10) and (12). Recall that $T_{2/0} - T_{1/0} = (1-p)T_{2/0}$ and, from the government budget constraint, $T_{2/0} = L_0/(1+p)$. Hence, for a given p, $T_{2/0}$, $T_{1/0}$, and $T_{2/0} - T_{1/0}$ are all positive functions of L_0 ; and for a given L_0 , $T_{2/0}$ and $T_{2/0} - T_{1/0}$ are negative functions of p.

The notion of fiscal stress is then captured by a high value of L_0 (i.e., high PDV of expected future expenditure and/or high initial debt) and by a low value of p (i.e., high expected taxation in the future). For brevity, I will refer to situations where L_0 is large and/or p is small as "bad times", and to the opposite situation as "good times".

Also for brevity, I will refer to the case of $\gamma_1 > 0$ as the 'keynesian' effects of government expenditure, and conversely to $\gamma_1 < 0$ as the 'non-keynesian' effects. Similarly, I will refer to the cases of $\gamma_2 < 0$ and $\gamma_2 > 0$ as the 'keynesian' and 'non-keynesian' effects of taxation, respectively. The 'expansionary effects of fiscal consolidations' occur when $\gamma_1 < 0$ and/or $\gamma_2 > 0$.

A. An expenditure shock.

Consider first the effects of a shock to government expenditure, summarized by γ_1 .⁸ By straightforward differentiation of the expression for γ_1 in (14), and assuming the sufficient condition $\theta_0 \leq 1$,⁹ it is easy to show the following

Result 1:

(i) γ_1 is a positive function of μ ; (ii) γ_1 is a negative function of L_0 .

(*iii*) γ_1 is a positive function of p.

The intuition is straightforward. Starting with part (i), the effect of an expenditure shock on aggregate consumption, γ_1 , is the weighted sum of its effects on the consumption of constrained and unconstrained individuals. From (12), the effect on the consumption of a constrained individual is just the positive disposable income effect β . From (10), the effect on the consumption of an unconstrained individual, $\frac{1+\theta_0}{2}(\beta - (1+2\lambda T_{2/0}))$, is negative if $\beta < 1$ or positive if $\beta > 1$ and $T_{2/0}$ is small, but in any case it is certainly smaller than the effect on a constrained individual. The reason is that, in addition to the positive effect β on the disposable income over the two periods, it also reflects a negative wealth effect from the expected future increase in T_2 (recall that T_1 is being held constant in this exercise). Hence, overall γ_1 is an increasing function of the weight of constrained individuals.

⁸Note that the results of the analysis would be qualitatively identical if an expenditurebased consolidation were defined as a permanent fall in the parameter \bar{G} or θ_0 in the process driving G_t , equation (5). Also, the degree of persistence of government consumption shocks, captured by θ_0 , affects the size of the effects of a given shock, but obviously does not change the qualitative conclusions of the analysis.

⁹This condition is needed only to prove part (i) of Result 1, and it is much more stringent than one needs.

intuition for part (ii) is also straightforward. Because of the convexity of tax distortions, the expected increase in T_2 following the increase in expenditure causes a bigger fall in the wealth and consumption of unconstrained individuals the larger the initial distortions, i.e. the higher the expected future tax rate $T_{2/0}$. In turn, $T_{2/0}$ is a positive function of L_0 . Similarly, part (iii)follows immediately from the fact that $T_{2/0}$ is a negative function of p. Figure 1 summarizes Result 1 and introduces the next Corollary:

Corollary 1:

(i) γ_1 is positive at low levels of L_0 and negative at high levels.¹⁰. (ii) γ_1 is positive at high levels of p and negative at low levels of p. That is, a government expenditure shock has keynesian effects when L_0 is low or p is high, and non-keynesian effects in the opposite case.

Part (i) of Corollary 1 follows immediately from Result 1. The intuition is once more straightforward: if L_0 is small, the wealth effect on unconstrained individuals γ_1^u , which is a direct function of L_0 , is either positive or negative but small in absolute value; hence the positive keynesian effect γ_1^c , which is independent of L_0 , dominates the aggregate effect. If L_0 is large, the effect of an expenditure shock on unconstrained individuals is certainly negative and becomes larger in absolute value as L_0 increases, until eventually it dominates the aggregate effect. A similar reasoning proves part (*ii*) of Corollary 1, recalling that $T_{2/0}$ is a negative function of p.

B. A revenue shock.

Now consider the effects of a positive realization of the tax shock ϵ_1^T . This shock causes taxes to go up in period 1 and to go down in period 2, relative to their expectations in period 0, but it does not affect the PDV of expenditure and taxation. By differentiation of the expression for γ_2 in (14), one obtains the following

Result 2:

(i) γ_2 is a negative function of μ ;

(ii) γ_2 is a positive function of L_0 for $\mu < \bar{\mu}$, and a negative function of L_0

¹⁰Note that, if $\beta < 1$, Corollary 1 would also require the condition that μ not be too close to 0. When $\beta < 1$, the effect on unconstrained individuals is negative even at $L_0 = 0$, and if μ is small this effect would always dominate for all values of L_0

for $\mu > \overline{\mu}$, where $\overline{\mu} = (1-p)/(1+p)$; (*iii*) γ_2 is a negative function of p.

Part (i) of Result 1 is straightforward, and again simply reflects the fact that γ_2^u is positive and γ_2^c is negative. Part (ii) is more complicated than the corresponding part of Result 1. The key difference is that, unlike in the case of a spending shock, for a revenue shock the effects of the initial conditions are the opposite on unconstrained and constrained individuals: γ_2^u is positive and increases with L_0 (see expression (10)); γ_2^c is negative and increases, in absolute value, with L_0 . Thus, at high levels of μ , the effect of the initial debt L_0 on constrained individuals dominates, and the converse at low levels of μ . The intuition for part (*iii*) is straightforward: the higher p, the closer is the initial expected path of taxation to perfect smoothing, hence the smaller the increase in the wealth of unconstrained individuals from a positive tax shock in period 1. Figure 2 summarizes these findings and introduces the next

Corollary 2:

 $\overline{(i)}$ For $0 < \mu < \overline{\mu}$, γ_2 is negative at low levels of L_0 and positive at high levels;

(*ii*) For L_0 and λ sufficiently large, γ_2 is negative for high values of p and positive for low values.

That is, under the stated conditions a tax shock has keynesian effects at low levels of L_0 or high values of p, and non-keynesian effects at high values of L_0 or low values of p.

The intuition for part (i) is straightforward. As shown above, when $\mu < \bar{\mu}$ γ_2 is a positive function of L_0 . When L_0 is small, the positive wealth effect on unconstrained individuals from an increase in taxation is small because the initial distortions are relatively small; hence, γ_2 is negative because the negative effect on unconstrained individuals dominates. When L_0 is large, the positive wealth effect on unconstrained individuals dominates and γ_2 is positive. When $\mu > \bar{\mu}$, revenue shocks always have a keynesian effect because the behavior of constrained individuals always dominates. To prove part (ii), note that γ_2 is a negative function of p and it is always negative at high values of p. When instead p is small, $T_{2/0} - T_{1/0}$ is large; hence, the positive wealth effect on unconstrained individuals from an increase in T_1 dominates if L_0 is large enough, i.e. if the initial difference $T_{2/0} - T_{1/0}$ is large enough, and if λ is large enough, i.e. if tax distortions are relevant. In all these cases, the term "large enough" is relative to μ : the larger μ , the larger L_0 and λ must be for γ_2 to be positive at large values of p.

It is immediately apparent that Corollary 2 is more "fragile" than Corollary 1, in that the switch from keynesian to non-keynesian effects of taxation requires slightly more stringent conditions. The empirical results will be consistent with this observation.

5 Specification and estimation methodology.

I test the predictions of the model on a yearly panel of 19 OECD countries, described in section VI.A. The empirical analysis requires two preliminary steps. First, the fiscal policy innovations ϵ_t^G and ϵ_t^T and the forecastable change in disposable income $\Delta Y_{t/t-1}$ are not directly observable. They must first be estimated, an issue that I discuss in section VI.B; in this section, I will simply assume that these estimates are available. Second, a key aspect of the model is that the effects of fiscal innovations depend on the initial conditions. I make this dependence explicit by interacting the coefficients of the fiscal innovations with the regime dummy variable D_t , taking the value 0 when the country-year t belongs to the 'good times' regime and the value 1 when it belongs to the 'bad times' regime. The construction of this variable is discussed in section VI.C.

After these steps, an estimable form of equation (13) becomes:¹¹

(15)
$$\Delta C_t = \gamma_1 \hat{\epsilon}_t^G + \tilde{\gamma}_1 D_t \hat{\epsilon}_t^G + \gamma_2 \hat{\epsilon}_t^T + \tilde{\gamma}_2 D_t \hat{\epsilon}_t^T + \mu \Delta Y_{t/t-1} + \omega_t$$

where $\Delta Y_{t/t-1}$ stands for the anticipated (from the perspective of t-1) change in Y between t and t-1, i.e. $\Delta Y_{t/t-1} = Y_{t/t-1} - Y_{t-1}$; a ' $^{\prime}$ denotes an estimate; γ_1 represents the effects of government expenditure in good times,

¹¹Equation (15) displays the key differences with the methodology of Giavazzi and Pagano [1996]. These authors estimate an error-correction model of consumption, rather than a Euler equation as here; more importantly, they use the first difference in government consumption and taxation as regressors, and then instrument them using variables lagged once and longer. This is equivalent to using the *anticipated* changes in taxation and expenditure, rather than the *unanticipated* changes as here. However, anticipated changes in expenditure and taxation should have no effect on the change in consumption once the change in disposable income is also included in the regression.

and $\tilde{\gamma}_1$ the *difference* in the effects of government expenditure between bad and good times. A similar interpretation applies to the coefficients of the tax shocks, γ_2 and $\tilde{\gamma}_2$. By Corollaries 1 and 2, under the null hypothesis $\gamma_1 > 0$, $\tilde{\gamma}_1 < 0, \gamma_2 < 0$, and $\tilde{\gamma}_2 > 0$.

 $\tilde{\gamma}_1 < 0, \, \gamma_2 < 0, \, \text{and} \, \tilde{\gamma}_2 > 0.$ Also, in (15) $\omega_t = \eta_t + \gamma_1(\epsilon^G_t - \hat{\epsilon}^G_t) + \tilde{\gamma}_1 D_t(\epsilon^G_t - \hat{\epsilon}^G_t) + \gamma_2(\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) \text{ and } (\epsilon^T_t - \hat{\epsilon}^T_t) + \tilde{\gamma}_2 D_t(\epsilon^T_t - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \Delta \hat{Y}_{t/t-1}), \text{ and the terms } (\epsilon^G_t - \hat{\epsilon}^G_t) + \mu(\Delta Y_{t/t-1} - \hat{\epsilon}^T_t) + \mu(\Delta Y_{t/t-1} - \hat{$

Consistent estimation of the coefficients of (15) also requires that $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ be uncorrelated with ω_t , or, equivalently, that $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ be uncorrelated with η_t . There are two main reasons why fiscal policy can respond to contemporaneous changes in the economic environment: automatic mechanisms and the reaction function of policymakers. The cyclical adjustment of fiscal policy, which I discuss in section VI.C below, has the purpose of eliminating the first source of endogeneity of fiscal policy. Hence, from now on $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ should be interpreted as the cyclically adjusted fiscal shocks. The identifying assumption of the model then rests on the notion that the policymakers are unlikely to respond much to the economic environment within a year. This is probably a safe assumption regarding government spending on goods and services, particularly its wage component. Changes in government employment must be legislated and implemented, and both processes take time; discretionary changes in government wages are usually the results of long negotiations with unions, which typically take place at intervals of one or more years.¹³

¹²As it is well known, a moving average structure would arise if ϵ_t in equation (1) is interpreted as a taste shock, or because of time aggregation: see e.g. Campbell and Mankiw [1990].

¹³An important issue is the effects of a price shock on the real amount of government consumption. If government consumption is legislated in nominal terms, a price shock will be reflected one to one in a fall in real government consumption. On the other hand, if government consumption is indexed with a lag less than a year, price shocks will have little effect on the real value of government consumption. Government wages are in general indexed, and non-wage government consumption - like government procurement

In principle, discretionary changes in taxation are easier and faster to decide and implement. Hence, the assumption of no or weak feedback from GDP is less tenable than in the case of government consumption. To take care of this problem, one would need quarterly data; but the type of data used in the present empirical analysis is not available at a quarterly frequency except for a few of the countries in the sample. However, note that the focus of the analysis is on the *difference* in the coefficients of tax surprises in good and bad times. Even if the estimated surprises are not truly exogenous, this is likely to bias *both* coefficients upward, but it is not clear why it should seriously bias their difference. Finally, this particular cause of endogeneity of revenues might not be too serious to begin with: major changes in taxation are usually passed in the main budget, towards the end of the fiscal year for the next fiscal year, or at most in the mid-year budget, but taking effect at the end of the year. If instead they are decided at the beginning of the year, obviously they cannot take into account the shock to GDP, and therefore there would be no endogeneity to start with. Thus, major discretionary changes in taxation are likely to affect, at most, only a small part of the tax revenues of a given year.

Instead of forecasting the change in disposable income using lagged information only, as in equation (15), one could also use the (cyclically adjusted) $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ as instruments. As argued above, these are valid instruments for ΔY_t if the model is to be identified. Let $\Delta Y_{t/t}$ be the change in disposable income estimated using past information and the contemporaneous estimated innovations in G_t and T_t . From (3), $\Delta Y_{t/t} = \Delta Y_{t/t-1} + \beta \hat{\epsilon}_t^G - (1+2\lambda T_{1/0}) \hat{\epsilon}_t^T$.¹⁴ The term $\mu \Delta Y_{t/t}$ now incorporates the effects of fiscal shocks on the disposable income of constrained individuals; hence, the coefficients of the fiscal shocks now reflect only the wealth effects on unconstrained individuals. In fact, using (12) $\mu\beta = \gamma_1^c$ and $-\mu(1+2\lambda T_{1/0}) = \gamma_2^c$, and by simple manipulation of (15) this approach is equivalent to estimating:

(16)
$$\Delta C_t = \gamma_1^u \hat{\epsilon}_t^G + \tilde{\gamma}_1^u D_t \hat{\epsilon}_t^G + \gamma_2^u \hat{\epsilon}_t^T + \tilde{\gamma}_2^u D_t \hat{\epsilon}_t^T + \mu \Delta \hat{Y}_{t/t} + \tilde{\omega}_t$$

- also typically includes indexing clauses. Thus, the truth probably lies between the two extreme cases of full and no indexation; where exactly the truth lies, however, depends on the specific country in a way that is difficult to quantify.

¹⁴For simplicity, this expression replaces the estimated coefficients with their actual values. Asymptotically, this makes no difference.

Comparing the coefficients of (16) to those of (15), and using (10) and (14), under the null hypothesis $\gamma_1^u < \gamma_1$, $\tilde{\gamma}_1^u = \tilde{\gamma}_1 < 0$, $\gamma_2^u > 0 > \gamma_2$, and $\tilde{\gamma}_2^u > \tilde{\gamma}_2 > 0$.

These relationships are intuitive. Although its actual sign depends on β , γ_1^u is certainly smaller than γ_1 because it also incorporates a negative wealth effect from future increases in taxation. From (14), $\tilde{\gamma}_1 = \tilde{\gamma}_1^u + \tilde{\gamma}_1^c$; but from (12), the effect of government expenditure on constrained individuals does not depend on the regime; hence $\tilde{\gamma}_1^c = 0$ and $\tilde{\gamma}_1 = \tilde{\gamma}_1^u$ because both reflect only the difference in the wealth effect on unconstrained individuals. γ_2^u is positive, because the wealth of unconstrained individuals increases when T_1 increases and T_2 decreases, holding constant their sum. Finally, $\tilde{\gamma}_2 = \tilde{\gamma}_2^u + \tilde{\gamma}_2^c$; however, now the negative effect of tax shocks on constrained individuals is stronger in bad times, hence $\tilde{\gamma}_2^c < 0$ and therefore $\tilde{\gamma}_2^u > \tilde{\gamma}_2$. Thus, this alternative approach allows one to test specifically the source of the non-keynesian effects of fiscal policy, namely wealth effects on unconstrained individuals.

I estimate equation (16) using an IV GMM estimator that allows for serial correlation of order 1 and heteroskedasticity of general form, essentially using the panel equivalent of the Newey-West variance covariance matrix (see Appendix A).¹⁵ To construct this matrix, one needs the residuals from a preliminary regression of ΔC_t on the r.h.s variables of equation (16), but

¹⁵This is the same type of estimator used by Attanasio and Browning [1995] and Attanasio and Weber [1995]. I also estimated all the standard errors with a variance covariance matrix that allows for contemporaneous correlation across countries. This variancecovariance matrix is constructed by adding a new component to the previous matrix. The new component must be weighed by a number between 0 and 1 to ensure that the resulting matrix is positive definite. The heteroskedasticity component also has to be weighed by a number between 0 and 1, but for this we have analytical results on the kernel that guide this choice; for instance, Newey and West [1987] show that $\theta = 1$ is the lowest value in the kernel $A(k,L) = (L+1-k)^{\theta}/(L+1)$ (where k is the lag in the residual) that ensures positive definiteness. In the case of the contemporaneous correlation component, there is no such guidance; in fact, positive definiteness is typically ensured in my regressions if the weight of the heteroskedasticity component is of the order of .01, which means that it makes virtually no difference whether the variance-covariance matrix allows for contemporaneous correlation across countries. For this reason, the standard errors I report are based on a covariance matrix that only allows for serial correlation and heteroskedasticity. However, all regressions include a set of year dummies, which should largely take care of the contemporaneous correlation.

with or $\Delta Y_{t/t}$ replaced by ΔY_t . Note that this procedure automatically provides an efficient estimator and asymptotically correct standard errors, i.e. it automatically takes care of the 'generated regressor problem' arising from the fact that $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ are obtained from forecasting regressions (see Pagan [1984] and Murphy and Topel [1985]).¹⁶

Before actually carrying out the estimation of (15) or (16), it is necessary to scale the variables appropriately. In a typical Euler equation involving consumption and disposable income only, the choice of the scaling factor would make little difference because the private consumption to income ratio is very similar across countries and over time. Hence, expressing all variables in log differences, as it is often done, would be appropriate. By contrast, there are large differences in the government consumption- and tax-to-GDP ratio, both over time and across countries. One would not expect a given percentage change in government consumption to cause the same percentage change in private consumption when government consumption is 10 percent of GDP as when it is 30 percent of GDP. Hence, the appropriate scaling factor in this case is the lagged value of disposable income, rather than the lagged own value as in the log-difference specification. Thus, from now on the notation ΔX_t will indicate the change in the real¹⁷ per capita value of the variable X_t , divided by the lagged value of real disposable income. Finally, as mentioned above ϵ_t in equation (1), which is one component of the error term ω_t , is likely to be an MA(1) process. The instruments must then be lagged twice; but note that $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ remain valid instruments even under this assumption.

¹⁶The estimation of equation (14 involves a two-step procedure: first the fiscal shocks $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ and the predicted values of disposable income $\hat{Y}_{t/t-1}$ are generated, then ΔC_t is regressed on them. Asymptotic efficiency and consistency of the standard errors follow from the fact that $\hat{Y}_{t/t-1}$ is orthogonal to $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ (see Pagan [1984]).

¹⁷All variables are deflated using the disposable income deflator. Conceptually, this is the right deflator to use, since what enters the definition of wealth of the private sector is the present discounted value of government consumption and taxes, expressed in terms of the deflator for disposable income. Not surprisingly, the behavior of the disposable income deflator is highly correlated with the consumption deflator.

6 The data and preliminary empirical issues.

A. The data.

The sample consists of a panel of 19 OECD countries, from as far back as 1965 to $1994.^{18}$ The data and their sources are described in detail in the Data Appendix. The budget variables used in this paper come from the *Economic Outlook* and *Revenue Statistics of Member Countries*, both published by the OECD. The well-known advantage of these datasets is that they use a uniform definition of all variables across countries and refer to the general government. Clearly, from the point of view of the private sector what matters is taxation and expenditure of the general government. The debt data come from the OECD *Economic Outlook* and, for the first years of the sample in a few countries, from the national sources described in the Data Appendix.¹⁹

B. The forecasting equations.

The fiscal policy innovations $\hat{\epsilon}_t^G$ and $\hat{\epsilon}_t^T$ are estimated according to the following procedure. For each country, I specify three parsimonious near-VAR's with government expenditure, taxes, and GDP as the endogenous variable. The first system has the form:

$$\Delta G_{t} = \alpha_{1,0} + \alpha_{1,1} \Delta G_{t-1} + \alpha_{1,2} \Delta T T_{t-1} + \alpha_{1,3} \Delta Q_{t-1} + \epsilon_{t}^{G}$$

$$(17) T_{t} = \alpha_{2,0} + \alpha_{2,1} \Delta G_{t-1} + \alpha_{2,2} \Delta T_{t-1} + \alpha_{2,3} \Delta Q_{t-1} + \epsilon_{t}^{T}$$

$$\Delta Q_{t} = \alpha_{3,0} + \alpha_{3,1} \Delta G_{t-1} + \alpha_{3,2} \Delta T T_{t-1} + \alpha_{3,3} \Delta Q_{t-1} + \alpha_{3,4} \Delta Q_{t-2} + \epsilon_{t}^{Q}$$

where T_t is the tax variable which is being forecasted (income and social security taxes paid by employees, or the same plus indirect taxes), TT_t is

¹⁹For a few year at the beginning of the sample in a few countries (Austria 1965-70, France 1965-77, Norway 1965-70, and Portugal 1965-70), data on general government debt are not available. For these country-years, I multiply the value of the central government debt by the ratio of general to central government debt in 1971 (1978 for France).

¹⁸The countries are: Australia, Austria, Belgium, Canada, Denmark, Finland, France, Germany, Greece, Ireland, Italy, Japan, Netherlands, Norway, Portugal, Spain, Sweden, United Kingdom, and United States. I exclude Switzerland from the sample because of the lack of data on cyclically adjusted taxes. The actual length of the sample depends on the country and on the tax variable used. Also, the first three years of the sample are lost to forecast the shocks.

total tax revenues, and Q_t is GDP. The second specification of the forecasting systems adds ΔG_{t-2} to the list of regressors of the government consumption equation, and ΔT_{t-2} to the list of regressors of the tax equation. The third specification of the system adds ΔQ_{t-2} to both regressions. In the benchmark regressions that I present below, for each country and for each variable I choose the specification with the highest R^2 . In each regression, the constant is allowed to change in 1975.²⁰

I cyclically adjust the tax shocks using the simple methodology proposed by Blanchard [1993]. Using GDP-elasticities of taxes provided by the OECD²¹, ϕ_t , for each country I compute the cyclically-adjusted tax innovation as $\hat{\epsilon}_t^T - \phi_t \hat{\epsilon}_t^Q T_t$, where $\hat{\epsilon}_t^T$ and $\hat{\epsilon}_t^Q$ are estimated from (17).²² The OECD has recently recomputed the income elasticities of taxes for 15 OECD countries²³ at about 4 years intervals, starting in 1978. For earlier periods, I assume the 1978 value of tax elasticities. This procedure is probably safe, since tax elasticities show minimal variation over time in each country, and moreover the period of substantial tax reforms starts after 1978.

²¹Note that these elasticities are not obtained from regressions, but from simulations based on the structure of the tax system of each country and on its distribution of earnings; hence, the cyclical component of the change in taxation is not a generated regressor.

²²The term T_t - the share of revenues to previous year's GDP - appears in the expression because $\hat{\epsilon}_t^T$ is defined as the innovation in revenues as shares of previous year's GDP. The original definition in Blanchard [1993] used unemployment, rather than real GDP, to cyclically-adjust taxes. Non-regression based elasticities of taxation to unemployment are not available. The elasticity ϕ_t I use is actually a weighted average of the elasticity of each component of tax revenue that appears in each specific definition of T_t .

²³These are all the countries in the sample, except Austria, Greece, Ireland, and Portugal. For these countries, I use older elasticities.

²⁰The system (17) implies a departure from the logic of the theoretical model, in that it does not impose the intertemporal government budget constraint in the estimation of the consumption equation. Doing so is a notoriously difficult and largely arbitrary operation, and I prefer not to impose a dubious restriction on my estimation procedure. Note also that, contrary to the theoretical model, it is impossible to make sure that the expected PDV of expenditure is being held constant when a shock to taxation occurs, even if the contemporaneous shock to expenditure is being held constant. Thus, in practice the coefficient of the tax shock also includes any wealth effect from future changes in expenditure associated with the current shock to taxation. This is not necessarily a serious problem, however, since the main goal of this paper is to estimate the difference in the effects of fiscal shocks between bad and good times.

C. Bad and good times.

The regime dummy variable D_t is not directly observable, and must be proxied. Corollaries 1 and 2 have highlighted the two main fiscal policy determinants of the regime: L_{t-1} , and p, the probability of re-election. This section illustrates the construction of the empirical counterparts to these determinants.

I compute L_{t-1} as the sum of the "cyclically adjusted" government debt B_{t-1} and the PDV of future government expenditure, computed recursively from the estimate of a system like (17).²⁴ I then divide the cyclically adjusted L_{t-1} by trend GDP in t-1, Q_{t-1}^T , to obtain the variable l_{t-1} . This procedure has the purpose of eliminating the potential correlation with the disturbances ω_t and $\tilde{\omega}_t$ in equations (15) and (16), since at least one component of these disturbances, ϵ_t in equation (1), is likely to have an MA(1) structure.

According to the first definition of bad times, a given country-year t belongs to the bad time regime if l_{t-1} is greater than a certain cut-off value x. This generates the first bad times dummy variable, $D1_t$. In the benchmark case, x is the ninetieth percentile of the distribution of l_t , generating a total of 48 observations of bad time years. In section VII I also display results based on progressively looser definitions, where x is the eightieth and seventieth percentile. I denote these different versions of the bad time dummy variable $D1_t$ by $D1_t(.90)$, $D1_t(.80)$, $D1_t(.70)$.

The second determinant of the bad time regime, p, is essentially unobservable in this panel. However, note that this variable captures the extent of the departure from perfect tax-smoothing; a lower p means a lower $T_{1/0}$, and therefore, given expenditure, a larger deficit. Hence, in the second definition,

²⁴Debt is cyclically adjusted by subtracting the cyclical change in taxation relative to the previous year, as measured by the lagged percentage change in GDP times the average GDP elasticity of taxes. Future expected tax revenues and expenditure are evaluated at trend GDP, and the change in taxes to start the recursion in (17) is cyclically adjusted. I compute the PDV of future expenditure as the discounted sum - at a discount rate of .05 per year - of the first 5 years of future expenditure. At the prevailing ratios of expenditure to GDP ratios, computing the PDV over a long horizon would make the value of government debt almost irrelevant for the value of L_{t-1} . In addition, the forecasts of government expenditure are subject to large standard errors far into the future. However, when I compute the PDV of total government expenditure over a 10-year horizon instead, I obtain very similar results.

the bad time dummy variable is simply a function of the deficit. Specifically, a given country-year t belongs to the bad time regime if the cyclically adjusted deficit, as a share of trend GDP, exceeds a certain value x in the two previous years t - 1 and t - 2.²⁵ This generates the second definition of the bad times dummy variable, $D2_t$. In the benchmark case, the value of x is set at .04, generating 53 observations on bad time years. In section VII, I also experiment with values of x of .03 and .02, corresponding to 80 and 122 observations on bad time years, respectively. These different versions of the bad time dummy variable $D2_t$ are denoted by $D2_t(.04), D2_t(.03)$, and $D2_t(.02)$.

Table I lists all the country-years that belong to the bad time regime according $D1_t(.90)$, $D1_t(.80)$, $D2_t(.04)$, and $D2_t(.03)$. The table highlights an important difference between the two definitions. In column (1) the benchmark version of the first definition, $D1_t(.90)$, captures long period of time in a few high-expenditure countries; 5 countries are represented, and 3 of these represent 83 percent of the total observations of bad times. The distribution of bad time country-years becomes already more balanced under $D1_t(.80)$ (column (2)). Even in its benchmark version $D2_t(.04)$ (column (3)), the second definition of bad times generates a fairly balanced distribution of bad time episodes across countries and over time: now 14 countries experience at least 1 year of bad times, with 9 of them experiencing at least 3 years. Under $D2_t(.80)$, all countries except Australia have at least 1 year of bad time, and only 5 countries have 2 years or less.

Note that, strictly speaking, the two bad time dummy variables interact with each other (see expressions (10) and (12)). Allowing for all these interactive effects would lead to a large number of cross terms in the same regression, including triple interactions of the type $D1_t * D2_t * \hat{\epsilon}_t^G$. Therefore, I present regressions based on $D1_t$ and $D2_t$ separately. This also has the advantage of highlighting the role of each determinant of bad times more clearly. Note also that the interaction between the two types of determinants is much more important for the non-keynesian effects of taxes than of expenditure. In the latter case, even if p = 1 expenditure shocks can easily have non-keynesian effects; but tax shocks cannot have non-keynesian effects at or around p = 1.

 $^{^{25}\}mathrm{I}$ measure the deficit as the first difference in government debt.

7 Estimates.

A. Basic results.

Table II presents the first estimates of equations (15) (first two columns) and (16) (last two columns); thus, the coefficient being estimated are the γ_i 's and $\tilde{\gamma}_i$'s of equation (15) in columns (1) and (2), and the γ_j^u 's and $\tilde{\gamma}_j^u$'s of equation (16) in columns (3) and (4).

The difference between columns (1) and (2) is that the bad time dummy variable is $D1_t(.90)$ in column (1), and $D2_t(.04)$ in column (2), and similarly for columns (3) and (4). Taxes are defined as the sum of direct taxes on households and social security taxes paid by employees.²⁶ Initially, the government expenditure variable is current spending on goods and services, or government consumption. All regressions also include a full set of year and country dummies and the bad time dummy variable.

Recall that under the null hypothesis, in columns (1) and (2) $\gamma_1 > 0$, $\tilde{\gamma}_1 < 0$, $\gamma_2 < 0$, and $\tilde{\gamma}_2 > 0$. The estimates are remarkably consistent with this hypothesis.²⁷ Starting with column (1), in good times government consumption innovations have a large positive effect on private consumption: the estimated coefficient is γ_1 is 1.10, significant at the 1 percent significance level. But in bad times, this positive effect all but vanishes: the estimated value of $\tilde{\gamma}_1$ is -1.61, also significant at the 1 percent significance level. Thus, in bad times the effects of government consumption innovations on private consumption is *negative* and equal to -.51, with a p-value for a test of the difference from 0 of .05.

The pattern of the coefficient estimates for the tax variable is also consistent with the model. The estimate of γ_2 is negative and significant at the 1 percent level, and the estimate of $\tilde{\gamma}_2$ is positive, much larger than the absolute value of γ_2 , and significant at the 2 percent level. The estimated

 $^{^{26}}$ For Italy, the breakdown between social security taxes paid by employers and by employees is not available until 1974. To avoid losing the first 9 years of the sample, for Italy the benchmark definition of taxes includes all social security taxes. Alternative definitions, that include and/or social security taxes paid by employers, lead to very similar results.

²⁷The variables used to predict ΔY_t are ΔC_{t-2} , ΔY_{t-2} , ΔT_{t-1} , ΔG_{t-1} , ΔT_{t-2} , and ΔG_{t-2} . ΔC_{t-2} also enters interacted with the country dummies, to capture in a compact way country-specific dynamics (see Attanasio and Browning [1995]). ΔT_{t-1} and ΔT_{t-2} are cyclically adjusted.

coefficient of the change in disposable income, .65, is close to the value one would obtain by averaging estimates from Euler equations on various countries, as obtained for instance by Campbell and Mankiw [1991] or Jappelli and Pagano [1989].

In column (2), based on $D2_t(.04)$, the pattern of estimates is very similar to column (1), with the only difference that now the estimate of $\tilde{\gamma}_2$ is very small and not statistically significant.

Columns (3) and (4) present estimates of the $\tilde{\gamma}_i$'s in equation (16). As discussed in section V, now all coefficients of fiscal shocks capture only the wealth effect on unconstrained individuals, since the disposable income effect on constrained individuals is already incorporated in the disposable income term. As a consequence, under the null hypothesis $\gamma_1^u < \gamma_1$, $\tilde{\gamma}_1^u = \tilde{\gamma}_1 < 0$, $\gamma_2^u > 0 > \gamma_2$, and $\tilde{\gamma}_2^u > \tilde{\gamma}_2 > 0$.

These predictions are mostly borne out in the regressions. In column (3), to be compared with column (1), the estimate of γ_1^u is practically 0, much lower than the estimate of γ_1 in column (1); the estimate $\tilde{\gamma}_1^u$ is negative and significant, and not too far from the estimate of $\tilde{\gamma}_1$ in column (1). The effects of taxation are also uniformly higher, in an algebraic sense, in column (3) than in column (1), again reflecting the fact that now the coefficient only captures the positive wealth effect on unconstrained individuals. In fact, γ_2^u in good times is now *positive* at .13, although not significant. The only point estimate inconsistent with the null hypothesis is that of $\tilde{\gamma}_2$ in column (3), which is smaller than the estimate $\tilde{\gamma}_2$ in column (1). Similar considerations apply to column (4) as compared to column (2). Note, however, that in columns (3) and (4) the coefficients of the tax variables are never significantly different from 0, although the estimates of γ_1^u are significantly different from the estimates of γ_1 in columns (1) and (2).

Thus, the key message of Table II is that there is a large difference in the effects of government consumption in bad and good times. The evidence on non-keynesian effects of taxation is slightly weaker: it supports the null hypothesis under $D1_t(.90)$, less so under $D2_t(.04)$.

B. The role of credit constraints.

Table III investigates the role of credit constraints in the transmission of fiscal shocks. The larger the share of unconstrained individuals, the larger the weight of the negative wealth effect of expenditure shocks and of the positive wealth effect of tax shocks in the aggregate effect. Accordingly, by Results 1 all coefficients of expenditure shocks in equations (15) and (16) are negative functions of the degree of development of credit markets; similarly, by Result 2 all coefficients of tax shocks are positive functions of the same variable.

A proxy for the degree of developments of credit markets has been constructed by Jappelli and Pagano [1994] in the context of a study on savings, liquidity constraints, and growth. The proxy they use is the maximum ratio of the loan to the value of the house in housing mortgages (LTV). This measure is available for each decade after 1960 for all countries in the present study, plus a few others. Hence, I assign each decade in the 19 countries in the sample to one of two subsamples, using a cut-off value of 80 percent for the LTV ratio. This cut-off point coincides exactly with the median, as it generates two groups of high-LTV and low-LTV country-decades with 240 and 241 observations, respectively. The Data Appendix lists all the observations on high- and low-LTV country-decades.

Columns (1) and (2) of Table III estimate the same specification as column (1) in Table II (i.e., based on $D1_t(.90)$), but on the sample of high- and low-LTV countries, respectively. Columns (3) and (4) do the same on the specification of column (2) of Table II (i.e., based on $D2_t(.04)$).

The results on expenditure shocks conform very well with expectations. Consistent with Result 1, in high-LTV countries both γ_1 and especially $\tilde{\gamma}_1$ are much smaller, algebraically, than in low-LTV countries, for both $D1_t$ and $D2_t$. Thus, in bad times negative government consumption shocks have large expansionary effects only in high-LTV countries; in low-LTV countries the impact of government consumption shocks on private consumption is always positive, and practically the same in bad and good times.

The results concerning the effects of a tax shock in high- and low-LTV countries are more mixed. γ_2 is smaller in low- than in high- LTV countries under $D1_t$ (columns (1) and (2)), but not under $D2_t$ (columns (3) and (4)). On the other hand, $\tilde{\gamma}_2$ is larger in high- than in low- LTV countries under $D2_t$, but not under $D1_t$. The estimates of $\tilde{\gamma}_2$, however, are rarely significant.

Notice that under both $D1_t$ and $D2_t$ the coefficient of the change in disposable income is much higher in low- than in high-LTV countries, as one would expect.

In summary, Table III confirms the impression of Table II: the empirical results are highly consistent with the theory as regards the effects of government expenditure, while the results for taxation are less strong, although one could always cite a regression which is reasonably favorable to the theory.

C. Alternative definitions of government expenditure.

The government expenditure variable so far was defined as current government spending on goods and services. Table IV presents estimates of the basic specifications of columns (1) and (2) in Table II, but using progressively larger definitions of the expenditure variable: total (including capital) expenditure on goods and services columns (1) and (2)), and total primary government expenditure (columns (3) and (4)).²⁸

For both bad time dummy variables the pattern is clear: the estimates of γ_1 fall as the government expenditure variable encompasses more items, while the estimates of $\tilde{\gamma}_1$ increases algebraically. It remains true, however, that these coefficients remain statistically significant: for all these definitions of government expenditure, there is always a structural change in the effects of government expenditure on private consumption in bad times.

A tentative explanation of this pattern can be based on the results of Alesina and Perotti [1995], [1997a]. On average, reductions in the budget deficit in OECD countries are much more persistent when implemented via government consumption cuts than capital expenditure cuts or via increases in taxation. The role of transfers can be explained by thinking of transfers as negative taxes; in all the regressions presented so far, taxes have a consistently smaller effect (in absolute value) than government consumption, and as we have seen there is much weaker evidence of a change in the effects of taxation during bad times.

D. Alternative definitions of bad times.

Table V explores the effects of progressively loosening the definition of bad times. In columns (1) and (2), the cut-off values for $D1_t$ are the 80th and the 70th percentile, respectively, instead of the 90th percentile in column (1) of Table II. This generates 96 and 145 'bad times' country-years, respectively. In columns (3) and (4), the cut-off values for the definition of $D2_t$ are .30 and .20 instead of .40 in column (2) of Table II. This generates 80 and 122 'bad times' country-years.

The estimated values of $\tilde{\gamma}_1$ decline slightly in absolute value as the definition becomes looser, but it remains significant throughout. The estimated values of $\tilde{\gamma}_2$ display a less clear pattern under $D1_t$; they rise and becomes more significant under $D2_t$ as the cut-off point is relaxed.

 $^{^{28}}$ Total government expenditure includes total expenditure on goods and services, transfers to households, and subsidies.

The general conclusion is that, up to the first 25-30 percent of the sample, the evidence on a drastic change in pattern of the effects of government spending is very strong, while again the conclusion must be nuanced in the case of taxes.

E. Influential countries.

The purpose of Table VI is to study whether certain countries have a disproportionate impact on these results. Column (1) displays the same benchmark regression of column (1) in Table II, but excluding 1 country at a time; for each coefficient, this column reports the smallest estimate (in absolute value) out of the 19 regressions one can run excluding one country at a time, and the country which is being excluded when this smallest estimate is obtained. Thus, this column can be interpreted as displaying the 'least favorable' regressions from the point of view of the theory, particularly when the values of $\tilde{\gamma}_1$ and $\tilde{\gamma}_2$ are considered. By contrast, column (2) displays the largest coefficient, in absolute value, and therefore can be interpreted as showing the 'best' regressions. Columns (3) and (4) do the same, but on the alternative definition of bad times, $D2_t$.

The first two columns deliver two key messages. The estimates of γ_1 are very robust: no matter which country is excluded, they are always highly significant. The estimates of $\tilde{\gamma}_1$, appears to be less robust: the exclusion of Sweden causes the estimated value to drop to -1.00 from 1.61, with a p-value of .12. However, in evaluating this result one should keep in mind that Sweden represents almost 40 percent of the sample of bad times years under the benchmark definition of $D1_t$. In fact, when the bad times dummy variable is $D2_t$ (columns (3) and (4)), or when a looser definition of $D1_t$, such as $D1_t(.80)$ or $D1_t(.70)$, is assumed (not shown), the estimate of $\tilde{\gamma}_1$ does not become insignificant when Sweden is excluded.

The second key message is that the estimates of the coefficients of tax shocks in good times, γ_2 , is also very robust. Under $D1_t$, it oscillates between a maximum of -.28 when Denmark is excluded, with a t-statistic of 2.43, and a minimum of -.38 when Sweden is excluded. Under $D2_t$, it oscillates between a maximum of -.20 when Denmark or Ireland are excluded, with tstatistics of 1.92 and 2.03 respectively, and a minimum of -.30 when Sweden is excluded. The estimates of $\tilde{\gamma}_2$, however, is less robust: under $D1_t$, and when the Netherlands is excluded, its t-statistic drops to 1.55; under $D2_t$, its t-statistics never reaches the value of 1. Under $D2_t$, the estimate of $ga\tilde{m}ma_2$ is insignificant to start with, and remains such no matter which country is excluded.

8 Discussion and conclusions.

As mentioned above, as a model of the effects of taxation, the present model has a similar logic to that of Blanchard [1990] and Sutherland [1997]. There, individuals expect that when the debt/GDP ratio hits a certain level \bar{b} , a large and very disruptive upward jump in taxation will occur, thereby reducing the wealth of currently alive individuals. A consolidation that occurs before the debt/GDP ratio reaches \bar{b} eliminates the need for this large tax increase, and therefore can have positive wealth effects. Thus, the logic of these models is similar to a "Peso problem", in that the behavior of the private sector is driven by the expectation of a rare and momentous event that might not have materialized in the sample. The common element with the present model is that, in expectation, the path of taxation is not flat. The reason, however, is different, and as a result the present model does not require a large discontinuity in the reaction function of policymakers (at the threshold level of debt/GDP ratio \bar{b}), or in the expectations of individuals. A second difference is that my model does not rely on a "Peso-problem" logic.

The only model I am aware of designed explicitly to capture the effects of government expenditure in the type of episodes mentioned above is Bertola and Drazen [1993]. The framework there is wholly neoclassical, in that individuals are infinitely lived and government consumption is pure waste. Hence, normally a consolidation via a cut in government consumption increases human wealth and is associated with an increase in private consumption. However, at high levels of debt it can be associated with *lower* private consumption. The reason is once again a discontinuity in the reaction function of policymakers. Individuals expect a large cut in government consumption - and therefore a large *increase* in wealth - when the government consumption/GDP ratio hits a threshold value \bar{g} ; any reduction in government consumption before that reduces the probability of reaching \bar{g} soon, and therefore it has a negative wealth effect. Hence, at high levels of debt the model implies a *positive* association between government consumption and private consumption, the opposite of what the present model delivers.²⁹ The

²⁹The Bertola and Drazen model is designed to fit the correlation between the government consumption/GDP ratio and the private consumption/GDP ratio observed in many

key difference in my model is that, in addition to the standard neoclassical wealth effect, government consumption also has a positive demand effect. For the overall effect to switch sign at higher levels of government consumption (or debt, as in my model), one also needs the coexistence of constrained and unconstrained individuals.

Exactly what types of wealth effects are captured in the regressions of the present paper is not easy to assess. Fiscal policy can affect human wealth by impacting on the size of future disposable income, given interest rates: this is the mechanism discussed in the model developed in the paper. Alternatively, it can affect wealth by impacting on nominal and real interest rates, given the flow of future disposable income. If a consolidation reduces nominal interest rates, the value of assets denominated in nominal terms increases; because bad times are normally associated with high levels of public debt, this is a potentially important source of asymmetry between normal and difficult times. Similar considerations apply to a fall in the real interest rate.

Disentangling these effects is difficult in the present context. One would need information on the market value of government debt, of the housing stock, and of the stock market. These variables exist only for a few countries in the present sample, and are often of dubious quality. Alternatively, one could study the relationship between fiscal policy innovations and interest rate innovations, which would require a larger VAR and, probably, quarterly data. A related problem which is difficult to address in the present context is that of the policies associated with fiscal consolidations. If there is a set of monetary and exchange rate policies that systematically accompany cuts in government consumption in difficult times, their effects would obviously be picked up by the fiscal policy coefficients in the regressions displayed above. Note, however, that for this to happen, these policies should help predict future wealth independently of their effects on current disposable income.

A second candidate explanation for the results of this paper is substitution effects from interest rate changes. If a fiscal policy shock causes a

episodes of consolidations, like Ireland and Denmark in the eighties. There, as government consumption as a share of GDP fell sharply, private consumption increased substantially, as discussed in the introduction. However, it *fell* as a share of GDP, but only because investment and net exports increased even more. Because in the Bertola-Drazen neoclassical model GDP is constant, there is no difference in the signs of the movements of private consumption and of the private consumption/GDP ratio. But in reality, the difference was sharp.

temporary fall in interest rates, consumers would try to take advantage of the temporarily low intertemporal price of consumption. This 'temporariness hypothesis' figures prominently in the analysis of the consumption booms in Latin America (see e.g. Rebelo and Vegh [1995] for a survey), but it is unlikely to be an important factor in the present context.

The most visible episodes of 'consumption booms' in Latin America are almost invariably associated with 'exchange-rate based stabilizations' (see e.g. Rebelo and Vegh [1995] and Kiguel and Liviatan [1992]), and therefore with very specific policies and expectations. In particular, fiscal policy tends to be more lax under exchange-rate based stabilizations than under moneybased stabilizations (see Kiguel and Liviatan [1992]); hence, it seems difficult to characterize these episodes as 'expansionary fiscal consolidations'. Rather, what is driving the consumption booms is mostly the expectation of the failure of the stabilization, and therefore of a devaluation and a balance of payment crisis.

Lack of credibility of the type described above is unlikely to be the driving force of the evidence presented in this paper. The large balance of payment crises of Latin America are rarely, if ever, observed in the OECD group in the eighties, when most of the episodes of 'bad times' are concentrated. In addition, fiscal policy exhibit much less variability in OECD countries than in Latin America (see Gavin and Perotti [1997]). Finally, Reinhart and Vegh [1995] have convincingly argued that the intertemporal elasticity of substitution in consumption is too low to account for most of the observed changes in consumption even in Latin America.

A third candidate explanation for a significant coefficient of government expenditure surprises in a consumption regression is non-separability between private and public consumption: see Aschauer [1985], Campbell and Mankiw [1989] and Graham and Himarios [1991] for evidence on US data and Karras [1994] for evidence on cross-country data. While the conclusions of these contributions span the entire possible range, from complementarity to substitutability, this explanation is again unlikely to apply to the evidence presented here. In fact, it is not clear why private and government consumption should be good substitutes in difficult times, but not in normal times.

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Appendix A.

The variance covariance matrix is estimated as

(A.1)
$$\hat{V} = \left[(M'S)W^{-1}(M'S)' \right]^{-1}$$

M is the $(\bar{T}\mathbf{x}\bar{K})$ matrix of observations on the independent variables in regression (16) and S is the $(\bar{T}\mathbf{x}\bar{K}_S)$ matrix of instruments.³⁰ \bar{T} is the total number of observations, \bar{K} the number of independent variables, \bar{K}_S is the number of instruments. The matrix W is basically the sum of country-specific Newey-West variance covariance matrices:

(A.2)
$$W = \frac{1}{N} \sum_{i=1}^{N} \frac{1}{T_i} \sum_{k=-1}^{1} A(k, L) \sum_{t=1}^{T_i - k} \hat{\delta}'_{t+k} \hat{\delta}_t;$$

where $\hat{\delta}_t$ is the row vector $s_t \hat{u}_t$, and \hat{u}_t is the residual from the preliminary regression, and A(k, L) is the kernel. *i* indicates the country, and *N* is the total number of countries. \hat{u}_t is defined by:

(A.3)
$$\hat{u}_t = \Delta C_t - \hat{\gamma}_1^u \hat{\epsilon}_t^G - \hat{\tilde{\gamma}}_1^u D_t \hat{\epsilon}_t^G - \hat{\gamma}_2^u \hat{\epsilon}_t^T - \hat{\tilde{\gamma}}_2^u D_t \hat{\epsilon}_t^T - \hat{\mu} \Delta Y_t$$

Note that ΔY_t , not $\hat{\Delta Y}_{t/t}$, appears in equation (A.3).

³⁰In the first approach (equation (15)), the matrix M includes $\Delta Y_{t/t-1}$ instead of ΔY_t , and S is equal to M.

Data Appendix.

<u>Government debt</u>: all data refer to the general government and come from the OECD Economic Outlook dataset, with the following exceptions:

Australia 1965-94: Federal Reserve Bank of Australia Bulletin.

Austria 1965-70 (Central Government): United Nations Statistical Yearbook.

Denmark 1965-71: Danmarks Nationalsbank: Monetary Review.

France 1965-77 (Central Government): United Nations Statistical Yearbook. Ireland 1965-73: Central Bank of Ireland Bulletin.

Netherlands 1965-69: Central Bureau of Statistics.

Norway 1965-70 (Central Government): United Nations Statistical Yearbook. Portugal 1965-70 (Central Government): United Nations Statistical Yearbook.

Spain 1965-70: Banco de Espana, Informe Anual. Sweden 1965-94: Allman Manads Statistik, Statistik Centralbgvan.

Household disposable income: from OECD Economic Outlook, except: Ireland 1965-71: OECD National Income Accounts. Netherlands 1965-69: OECD National Income Accounts.

<u>Direct taxes on households</u>: from OECD Economic Outlook, except: Ireland 1965-69: OECD National Income Accounts. Ireland 1970-76: OECD Revenue Statistics of Member Countries, line nes1100, general government. Netherlands 1965-69: OECD National Income Accounts. Norway 1965-74: OECD Revenues Statistics of Member Countries.

Social security taxes paid by employees.: from OECD Revenue Statistics of *Member Countries*, lines nes2100 (paid by employees) + nes2300 (paid be self-employed), general government.

Italy: Social security taxes received by general government, *OECD Economic Outlook*.

<u>Indirect taxes</u>: from *OECD Economic Outlook*, except: Netherlands 1965-69: *OECD National Income Accounts*.

Government consumption: from OECD Economic Outlook, except: Ireland 1965-69: OECD National Income Accounts. Ireland 1970-76: OECD Revenue Statistics of Member Countries, line nes1100, general government.

Netherlands 1965-69: OECD National Income Accounts. Norway 1965-74: OECD Revenues Statistics of Member Countries.

<u>Loan-to-Value Ratio</u>: ratio of loan to value of house in average mortgage contract, from Jappelli and Pagano [1994].

Country-decades with Loan-to-Value ratio larger than 80 percent ("High-LTV"): Australia 1980-94, Canada 1980-94, Germany 1980-94, Denmark 1970-94, Spain 1980-94, Finland, France, UK 1970-94, Ireland, Norway 1980-94, Sweden, USA.

Country-decades with Loan-to-Value ratio less than 80 percent ("Low-LTV"): Australia 1965-80, Austria, Belgium, Canada 1965-80, Germany 1965-80, Denmark 1965-70, Spain 1965-80, Greece, Italy, Japan, Netherlands, Norway 1965-80, Portugal.

In some cases, the Loan-to-Value Ratio was not available. In these cases, I assigned a decade to the High-LTV or Low-LTV group of countries assuming that the Loan-to-Value ratio does not decrease over time, which is always true for the countries for which Jappelli and Pagano report data over time. Hence, if in country X the Loan-to-Value ratio is 70 percent in 1970-80, and it is missing in 1965-70, I assume the Loan-to-Value ratio in 1965-70 to be no greater than 70 percent, and hence I code 1965-70 in country X as Low-LTV. The UK does not have data 1965-70, and in 1970-80 the Loan-to-Value ratio is above 80 percent. Hence, I could not code the 1965-70 decade in the UK.

TABLE I

	(1)	(2)	(3)	(4)
	$D1_t(.90)$	$D1_t(.80)$	$D2_t(.04)$	$D2_t(.03)$
Australia				
Austria		1993	1978	1977-78
Belgium	1979 - 93	1974, 1976-93	1980-85, 1989	1980-89
Canada			1985 - 87	1985 - 87
Denmark	1984-86,	1981-94	1981 - 85	1978-85
	1988-94	1981-94	1981 - 85	1978-85
Finland		1993-94	1994	1994
France		1994		1994
Germany				1977
Greece			1986,	1985-86,
			1990-93	1989-93
Ireland		1986, 1988,	1985	1980, 1983-85,
		1992-94		1988
Italy	1992 - 94	1986-94	1973, 1985-89,	1973, 1984-90,
			1993	1993-94
Japan			1978-82	1969-70,
				1978-84
Netherlands	1988,	1980-94	1985-86	1985-86,
	1990-93			1990
Norway		1979-81,	1978-80,	1978-80,
		1987-94	1987	1987, 1994
Portugal		1993	1982, 1989	1982, 1989
Spain			1984-86	1984-1986, 1991
Sweden	1980-94	1978-94	1980-85, 1994	1980-85, 1994
United Kingdom				1994
United States				1985-87
Obs.	48	96	53	80

BAD TIMES

Column 1: 'bad time' dummy variable is $D1_t(.90)$, defined by $l_{t-1} > x$, where x is ninetieth percentile;

Column 2: 'bad time' dummy variable is $D1_t(.80)$, defined by $l_{t-1} > x$, where x is eightieth percentile; 37 Column 3: 'bad time' dummy variable is $D2_t(.04)$, defined by $b_{t-1} - b_{t-2} > x$ and $b_{t-2} - b_{t-2} > x$

 $b_{t-3} > x$, with x = .04;

Column 4: 'bad time' dummy variable is $D2_t(.03)$, defined by $b_{t-1} - b_{t-2} > x$ and $b_{t-2} - b_{t-2} > x$ $b_{t-3} > x$, with x = .03.

TABLE II

Var.	Coeff.	(1)	(2)	Coeff.	(3)	(4)
$\hat{\epsilon}^G_t$	γ_1	1.10 (5.82)	0.93 (4.58)	γ_1^u	0.01 (0.05)	-0.06 (0.34)
$D_t \ast \hat{\epsilon}^G_t$	$\tilde{\gamma}_1$	-1.61 (5.15)	-1.37 (2.61)	$\tilde{\gamma}_1^u$	-1.05 (3.00)	-1.14 (2.06)
$\hat{\epsilon}_t^T$	γ_2	-0.32 (3.08)	-0.23 (2.37)	γ_2^u	0.13 (1.09)	0.17 (1.58)
$D_t * \hat{\epsilon}_t^T$	$\tilde{\gamma}_2$.48 (2.32)	0.07 (0.24)	$\tilde{\gamma}_2^u$	0.40 (1.62)	0.22 (0.67)
$\hat{\Delta Y}_{t/t-1}$	μ	0.65 (6.31)	0.66 (6.42)			
$\hat{\Delta Y}_{t/t}$				μ	0.74 (8.53)	0.75 (8.22)
Sample		All	All		All	All
Nobs.		484	484		484	484
R^2 of first stage		0.37	0.37		.48	.47
Defn. of 'bad times'		$D1_t(.90)$	$D2_t(.04)$		$D1_t(.90)$	$D2_t(.04)$
No. of 'bad times'		48	53		48	53

FIRST ESTIMATES

Dependent variable: change in real, per-capita private consumption, scaled by previous year real per-capita disposable income. All regressions include a full set of year and country dummies and the dummy variable D_t . Government expenditure is defined as current spending on goods and services (government consumption). Columns (1) and (2) display estimates of equation (15), i.e. $\Delta Y_{t/t-1}$ is estimated using only past information. Columns (3) and (4) display estimates of equation (16), i.e. $\Delta Y_{t/t}$ is estimated using also the current fiscal shocks.

In columns (1) and (3) 'bad time' dummy variable is $D1_t(.90)$; in columns (2) and (4) 'bad time' dummy variable is $D2_t(.04)$. For the definition of $D1_t(.90)$ and $D2_t(.04)$ and a list of the country-years in each, see Table I.

TABLE III

Var.	Coeff.	(1)	(2)	(3)	(4)
_ĉ G	24	0.84	1 10	0.56	1 93
ϵ_t	1	(4.01)	(3.34)	(2.63)	(3.53)
$D_t * \hat{\epsilon}^G_t$	$\tilde{\gamma}_1$	-1.49	0.11	-1.49	-0.60
		(5.08)	(0.92)	(2.77)	(0.53)
$\hat{\epsilon}_t^T$	γ_2	-0.29	-0.50	-0.29	-0.33
		(2.50)	(2.47)	(2.65)	(1.87)
$D_t \ast \hat{\epsilon}_t^T$	$\tilde{\gamma}_2$	0.25	0.57	0.29	-0.11
		(0.96)	(1.86)	(1.00)	(0.20)
$\hat{\Delta Y}_{t/t-1}$	μ	0.53	0.87	0.55	0.93
		(5.99)	(4.56)	(6.73)	(4.91)
Sample		High-	Low-	High-	Low-
		LTV	LTV	LTV	LTV
Nobs.		240	241	240	241
\mathbb{R}^2 of first		0.28	0.43	0.28	0.44
stage		D1(00)	D1(00)	D9(04)	D9(04)
'bad times'		$D1_t(.90)$	$D1_t(.90)$	$D2_t(.04)$	$D2_t(.04)$
No. of		25	23	21	32
'bad times'					

THE ROLE OF CREDIT CONSTRAINTS

This Table displays estimates of (15), on the sample of high- and low-LTV countries separately. High-LTV: country-decades with Loan-to-Value ratio (from Jappelli-Pagano [1994] larger than 80% Low-LTV: country-decades with Loan-to-Value ratio less than 80%. See the Data Appendix for a list. The total number of observations of the two subsamples, 481, is less than the total number of observations of the whole sample, 484, because 3 observations in the sixties in the United Kingdom could not be assigned a value of LTV.

TABLE IV

		(1)	(2)	(3)	(4)
		Total exp.	Total exp.	Total	Total .
		goods and	goods and	prım.	prim.
		services	services	exp.	exp.
Var.	Coeff.				
$\hat{\epsilon}^G_t$	γ_1	0.68	0.64	0.35	0.35
		(5.04)	(4.75)	(4.75)	(4.57)
$D_t * \hat{\epsilon}^G_t$	$\tilde{\gamma}_1$	-1.06	-0.87	-1.31	-0.38
		(3.66)	(2.24)	(2.28)	(2.05)
$\hat{\epsilon}_t^T$	γ_2	-0.27	-0.21	-0.34	-0.26
		(2.78)	(2.29)	(3.46)	(2.74)
$D_t * \hat{\epsilon}_t^T$	$\tilde{\gamma}_2$	0.01	0.57	0.53	0.04
		(1.98)	(0.04)	(2.42)	(0.15)
$\hat{\Delta Y}_{t/t-1}$	μ	0.43	0.65	0.58	0.59
		(1.98)	(6.63)	(6.49)	(6.61)
Sample		All	All	All	All
Nobs.		484	484	484	484
R^2 of first		0.37	0.38	0.37	0.37
Defn. of 'bad times'		$D1_t(.90)$	$D2_t(.04)$	$D1_t(.90)$	$D2_t(.04)$
No. of 'bad times'		48	53	48	53

OTHER DEFINITIONS OF GOVERNMENT EXPENDITURE

This Table displays estimates of (15), using alternative definitions of the government expenditure variable G_t . Columns (1) and (2): government expenditure is total expenditure on goods and services. Columns (3) and (4): government expenditure is total primary expenditure.

TABLE V

Var.	Coeff.	(1)	(2)	(3)	(4)
$\hat{\epsilon}^G_t$	γ_1	1.19 (5.69)	1.26 (5.45)	0.95 (4.45)	0.98 (4.22)
$D_t \ast \hat{\epsilon}^G_t$	$\tilde{\gamma}_1$	-1.35 (4.14)	-1.32 (4.18)	-1.07 (2.40)	-0.90 (2.22)
$\hat{\epsilon}_t^T$	γ_{2}	-0.31 (2.82)	-0.38 (3.35)	-0.28 (2.62)	-0.35 (3.20)
$D_t * \hat{\epsilon}_t^T$	$\tilde{\gamma}_2$	0.34 (1.06)	0.57 (1.87)	0.32 (1.55)	0.47 (2.41)
$\hat{\Delta Y}_{t/t-1}$	μ	0.65 (6.69)	0.65 (6.71)	0.65 (6.26)	0.65 (6.22)
Sample		All	All	All	All
Nobs.		484	484	484	484
R^2 of first stage		0.37	0.37	0.37	0.37
Defn. of 'bad times'		$D1_t(.80)$	$D1_t(.70)$	$D2_t(.03)$	$D2_t(.02)$
No. of 'bad times'		96	145	80	122

OTHER DEFINITIONS OF BAD TIMES

This Table displays estimates of (15), using alternative versions of the bad time dummy variables $D1_t$ and $D2_t$. In column (1), $D1_t(.80)$ is defined by the condition $l_{t-1} > x$, where x is the eightieth percentile of the distribution of l_{t-1} . In column (1), $D1_t(.70)$ is defined similarly, but x is the seventieth percentile of the distribution of l_{t-1} . In column (2), $D2_t(.03)$ is defined by the condition $b_{t-1} - b_{t-2} > x$ and $b_{t-2} - b_{t-3} > x$, where x = .03. In column (4), $D2_t(.02)$ is defined similarly, but x = .02.

TABLE VI

Var.	Coeff.	(1)	(2)	(3)	(4)
$\hat{\epsilon}^G_t$	γ_1	0.83 (5.43)	1.16 (5.88)	0.65 (3.69)	1.13 (5.28)
excluded country		PRT	GRC	PRT	SWE
$D_t * \hat{\epsilon}_t^G$ excluded country	$\tilde{\gamma}_1$	-1.00 (1.54) SWE	-1.73 (5.34) ITA	-1.11 (2.29) PRT	-1.65 (3.00) GRC
$\hat{\epsilon}_t^T$ excluded country	γ_2	-0.28 (2.43) DNK	-0.38 (3.10) SWE	-0.20 (1.92) DNK	-0.30 (2.52) SWE
$D_t * \hat{\epsilon}_t^T$	$\tilde{\gamma}_2$	0.40 (1.55)	0.51 (2.69)	-0.07 (0.22)	0.18 (0.55)
excluded country		NLD	FIN	NLD	UT
$\hat{\Delta Y}_{t/t-1}$	μ	0.58 (6.50)	0.79 (6.44)	0.59 (6.69)	0.78 (6.05)
excluded country		PRT	DNK	PRT	DNK
Defn. of 'bad times'		$D1_t(.90)$	$D1_t(.90)$	$D2_t(.04)$	$D2_t(.04)$

INFLUENTIAL COUNTRIES

Columns (1) and (2) display the smallest and largest (in absolute values) estimates of each coefficient of equation (15), generated by excluding 1 country at a time in regression (1) of Table II (i.e., based on $D1_t(.90)$). For each estimate, the corresponding t-statistic and the country that is being excluded. Columns (3) and (4) do the same, but they apply to regression (2) in Table II (i.e., based on $D2_t(.04)$.





