

# Strategies and Interactive Beliefs in Dynamic Games

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- *Topic*: formal analysis of strategic thinking in dynamic games, backward and forward induction reasoning.
- *Tools*: epistemic (type) structures where states determine truth value of conditional statements.
- *Innovation*: we use **only epistemic conditionals** of the form: "if **i** learned **h** he would believe **E** with probability **p**";  
state=(actual actions,epistemic conditionals).
- *Motivation*: strategies cannot be (irreversibly) chosen, nor observed, they are just beliefs on own contingent choices (objective vs subjective strategies).
- *Focus*: generic perfect information games.

- 1 Preview on conditionals and BI: semi-formal analysis of an example
- 2 Setup: PI games and epistemic structures
- 3 Strategies as epistemic constructs: some results
- 4 Conclusions

# Preview: two kinds of type structures

Variants of Battigalli-Siniscalchi JET99: types are implicit representations of hierarchies of conditional beliefs. But, what are first-order beliefs about?

- $\mathbf{H}$ =histories,  $\mathbf{Z}$ =paths (terminal nodes),  $\mathbf{S}_i, \mathbf{S}_{-i}, \mathbf{S}$ =strategies
- "Traditional"  $\mathbf{S}$ -based structures:  $(\bar{\mathbf{T}}_i, \bar{\beta}_i)_{i \in I}$ , states in  $\Omega = \mathbf{S} \times \mathbf{T}$ ,  $(\mathbf{s}_i, \mathbf{t}_i)$ =state of  $i$  ( $\mathbf{s}_i$  is "objective"),  $\mathcal{H}_i$ =conditioning events,

$$\begin{aligned}\mathcal{H}_i &= \{\mathbf{S}_{-i}(\mathbf{h}) \times \bar{\mathbf{T}}_{-i} : \mathbf{h} \in \mathbf{H}\} \\ \bar{\beta}_i &: \bar{\mathbf{T}}_i \rightarrow \Delta^{\mathcal{H}_i}(\mathbf{S}_{-i} \times \bar{\mathbf{T}}_{-i}) \subset [\Delta(\mathbf{S}_{-i} \times \bar{\mathbf{T}}_{-i})]^{\mathcal{H}_i}\end{aligned}$$

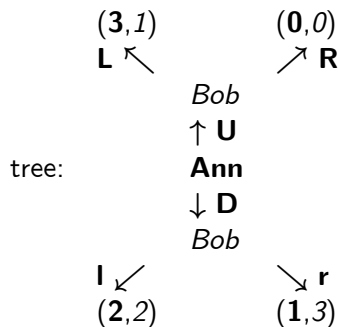
- Our  $\mathbf{Z}$ -based structures:  $(\mathbf{T}_i, \beta_i)_{i \in I}$ , states in  $\Omega = \mathbf{Z} \times \mathbf{T}$ ,  $\mathbf{t}_i$ =epist.state of  $i$  (beliefs about others+plan),

$$\begin{aligned}\mathbf{H} &\approx \{\mathbf{Z}(\mathbf{h}) \times \mathbf{T}_{-i} : \mathbf{h} \in \mathbf{H}\} \\ \beta_i &: \mathbf{T}_i \rightarrow \Delta^{\mathbf{H}}(\mathbf{Z} \times \mathbf{T}_{-i}) \subset [\Delta(\mathbf{Z} \times \mathbf{T}_{-i})]^{\mathbf{H}}\end{aligned}$$

# Preview on conditionals and BI: an example

## Stackelberg mini-game

outputs:	low (left)	high (right)
high (up)	<b>3,1</b>	<b>0,0</b>
low (down)	<b>2,2</b>	<b>1,3</b>



# Preview on conditionals and BI: an example

## Stackelberg mini-game

- *Ann believes "Bob would go Right given Up"*  
=belief about a behavioral conditional
- **Given Up**, *Ann would believe "Bob goes Right"*  
=conditional belief about behavior
- In **traditional analysis**: behavioral conditionals and beliefs about conditionals and opponents' beliefs
- In **our analysis**: actual actions (paths) and *conditional* beliefs about actions and beliefs
- Possible interpretation: static analysis of players' conjectures of what would be the case under different hypotheses (cf. Samet, GEB 1996)

# Preview on conditionals and BI: traditional analysis

States  $\omega$  specify strategies  $\mathbf{s}_i = \sigma_i(\omega)$  **objectively**

'Bob would go Right given Up' **false** at  $\omega$  iff  $\sigma_{\text{Bob}}(\omega) \in \{\mathbf{L.r}, \mathbf{L.l}\}$

$$\text{Rat}_{\text{Bob}} \subset [\mathbf{L.r}] = \{\omega : \sigma_i(\omega) = \mathbf{L.r}\} \Rightarrow \\ \mathbf{B}_{\text{Ann}}(\text{Rat}_{\text{Bob}}) \subset \mathbf{B}_{\text{Ann}}(\mathbf{L.r}) \text{ (uncond. belief)}$$



Bob  
 $\uparrow$  **U**  
**Ann**  
 $\downarrow$  **D**  
 Bob

States also specify conditional beliefs

By built in independence:

$$\mathbf{B}_{\text{Ann}}(\mathbf{L.r}) \subset \mathbf{B}_{\text{Ann}}(\mathbf{L}|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\mathbf{r}|\mathbf{D}) = \\ = \mathbf{B}_{\text{Ann}}(\text{util} = 3|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\text{util} = 1|\mathbf{D})$$

$$\Rightarrow \text{Rat}_{\text{Ann}} \cap \text{Rat}_{\text{Bob}} \cap \mathbf{B}_{\text{Ann}}(\text{Rat}_{\text{Bob}}) \subset \\ \subset [\mathbf{U}, \mathbf{L.r}] \subset [\mathbf{U}, \mathbf{L}]$$



$\Rightarrow$  **BI strategies and path obtain**

# Preview on conditionals and BI: our analysis

“strategy” is an epistemic concept:  
*i*'s cond. beliefs  $\Rightarrow$  contingent plan of *i*

Rat. Planning:  $\mathbf{RP}_{\text{Bob}} = \mathbf{B}_{\text{Bob}}(\mathbf{L}|\mathbf{U}) \cap \mathbf{B}_{\text{Bob}}(\mathbf{r}|\mathbf{D})$

Material Consistency = path cons. with plan

Material Rationality = Material cons. + Rat. plan.

$\mathbf{MR}_{\text{Bob}} \subset [\mathbf{U}, \mathbf{L}] \cup [\mathbf{D}, \mathbf{r}]$

But no event  $[\mathbf{L}, \mathbf{r}]$ .  $\mathbf{B}_{\text{Ann}}(\mathbf{L}, \mathbf{r})$  not expressible!

$\mathbf{B}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}) \subset \mathbf{B}_{\text{Ann}}([\mathbf{U}, \mathbf{L}] \cup [\mathbf{D}, \mathbf{r}]) \not\subset$   
 $\not\subset \mathbf{B}_{\text{Ann}}(\mathbf{L}|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\mathbf{r}|\mathbf{D})$  e.g. if  $\mathbf{B}_{\text{Ann}}(\mathbf{U}) = \mathbf{0}$



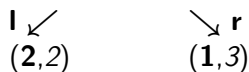
*Bob*

$\uparrow \mathbf{U}$

**Ann**

$\downarrow \mathbf{D}$

*Bob*





# Preview on conditionals and BI: an example

Our analysis

Recall:  $MR_{Bob} \subset [U, L] \cup [D, r]$ , but

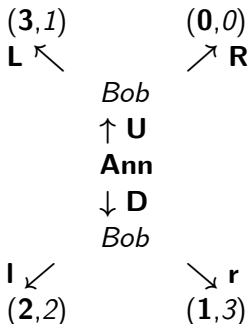
$B_{Ann}(MR_{Bob}) \not\subset B_{Ann}(L|U) \cap B_{Ann}(r|D)$  e.g. if  $B_{Ann}(U) = 0$

Since there is no event  $[L.r]$ ,  
 $B_{Ann}(L.r)$  not expressible

If  $B_{Ann}(D)$  (Ann plans  $D$ ) the following is possible

$B_{Ann}([U, L] \cup [D, r]) \cap \neg B_{Ann}(L|U)$

$\exists \omega \in [D, r] \cap MR_{Ann} \cap MR_{Bob} \cap B_{Ann}(MR_{Bob})$



⇒ **Imperfect Nash equilibrium may obtain**

# Preview on conditionals and BI: an example

How to recover elementary BI, route 1: Strong Belief in rationality

- Ann *strongly believes* **E** if she believes **E** given each **C** with  $\mathbf{C} \cap \mathbf{E} \neq \emptyset$
- $[\mathbf{U}] \cap \mathbf{MR}_{\text{Bob}} \neq \emptyset$ ,  $[\mathbf{D}] \cap \mathbf{MR}_{\text{Bob}} \neq \emptyset$
- hence  $\mathbf{SB}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}) \subset \mathbf{B}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}|\mathbf{D})$
- but  $\mathbf{MR}_{\text{Bob}} \subset [\mathbf{U}, \mathbf{L}] \cup [\mathbf{D}, \mathbf{r}]$
- hence  $\mathbf{SB}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}) \subset \mathbf{B}_{\text{Ann}}(\mathbf{L}|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\mathbf{r}|\mathbf{D})$  (BI cond. beliefs)
- thus  $\mathbf{MR}_{\text{Ann}} \cap \mathbf{MR}_{\text{Bob}} \cap \mathbf{SB}_{\text{Ann}}(\mathbf{MR}_{\text{Bob}}) \subset [\mathbf{U}, \mathbf{L}]$  (BI path)

# Preview on conditionals and BI: an example

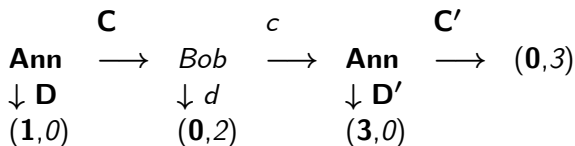
How to recover elementary BI, route 2: Own-Action Independence

- Suppose
  - (i) Ann's conditional beliefs about Bob's beliefs (hence his plan) are *independent* of her actions (**Ind**),
  - (ii) Ann strongly believes the Bob is materially consistent:
- $\mathbf{Ind} \cap \mathbf{B}_{\text{Ann}}(\mathbf{RP}_{\text{Bob}}) \cap \mathbf{SB}_{\text{Ann}}(\mathbf{MC}_{\text{Bob}}) \subset \mathbf{B}_{\text{Ann}}(\mathbf{L}|\mathbf{U}) \cap \mathbf{B}_{\text{Ann}}(\mathbf{r}|\mathbf{D})$
- Thus
  - $\mathbf{MR}_{\text{Ann}} \cap \mathbf{MR}_{\text{Bob}} \cap \mathbf{Ind} \cap \mathbf{B}_{\text{Ann}}(\mathbf{RP}_{\text{Bob}}) \cap \mathbf{SB}_{\text{Ann}}(\mathbf{MC}_{\text{Bob}}) \subset [\mathbf{U}, \mathbf{L}]$
- (Note: such independence and belief in consistency are implicit in traditional analysis)

- Route 1 (SB, with higher-level epistemic assumptions) leads to the BI-path in generic PI games
- Route 2 (OAI) leads to the BI-path in generic two-stage PI games, not in longer games such as the Centipede (even with higher-level epistemic assumptions)

# "Centipede" example: strong belief analysis

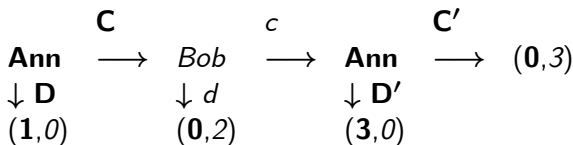
Forward induction reasoning yields the BI outcome



- $\mathbf{MR}_{\mathbf{Ann}} \subset \neg[\mathbf{C}, c, \mathbf{C}']$
- $\mathbf{MR}_{\mathbf{Bob}} \cap \mathbf{SB}_{\mathbf{Bob}}(\mathbf{MR}_{\mathbf{Ann}}) \subset [\mathbf{D}] \cup [\mathbf{C}, d]$
- $\mathbf{MR}_{\mathbf{Ann}} \cap \mathbf{SB}_{\mathbf{Ann}}(\mathbf{MR}_{\mathbf{Bob}} \cap \mathbf{SB}_{\mathbf{Bob}}(\mathbf{MR}_{\mathbf{Ann}})) \subset [\mathbf{D}]$

# "Centipede" example: initial common belief analysis

Not enough to get the BI outcome



- $\text{MR}_{\text{Ann}} \subset \neg[\mathbf{C}, c, \mathbf{C}']$
- But, if  $\text{SB}_{\text{Bob}}(\text{MR}_{\text{Ann}})$  is **not** assumed,  $\text{MR}_{\text{Bob}}$  has no behavioral implication! Thus
- $\text{MR}_{\text{Ann}} \cap \text{MR}_{\text{Bob}} \cap \text{Ind} \cap \text{B}_{\text{Ann}}(\text{RP}_{\text{Bob}}) \cap \text{SB}_{\text{Ann}}(\text{MC}_{\text{Bob}}) \subset \neg[\mathbf{C}, c, \mathbf{C}']$
- $\Rightarrow$  initial common belief in  $\text{MR} \cap \text{Ind} \cap \text{SB}(\text{MC})$  only buys  $\neg[\mathbf{C}, c, \mathbf{C}']$

(We can show this by example and as corollary of a general theorem)

# Setup

## Perfect Information (PI) games

- $i \in I$ , *players*
- $h \in H$ , *histories/nodes* ( $H_i$ , owned by  $i$ ),  $H$  **finite**
- $z \in Z \subset H$ , *terminal histories/paths*;  $Z(h) = \{z : h \preceq z\}$
- $a \in A(h)$ , *actions* at  $h \in H \setminus Z$
- $u_i : Z \rightarrow \mathbb{R}$ , *utility/payoff* s.t. **no relevant ties**

# Setup

## Epistemic structures for PI games: general

- $\omega \in \Omega$ , *states of the world*
- $x \in \mathbf{X}$ , *eXternal* (non-epistemic) *states*, **finite** (e.g.  $\mathbf{X} = \mathbf{S}$  or  $\mathbf{X} = \mathbf{Z}$ )
- (implicitly understood *path function*  $\pi : \mathbf{X} \rightarrow \mathbf{Z}$ )
- $\xi : \Omega \rightarrow \mathbf{X}$ ,  $\xi(\omega)$  external state at  $\omega$ ,  $[\mathbf{Y}] = \xi^{-1}(\mathbf{Y})$  external events
- $\hat{\beta}_i : \Omega \rightarrow \Delta_i$ ,  $\hat{\beta}_i(\omega)$  epistemic state at  $\omega$  ( $\Delta_i = \mathbf{Beliefs}_i$  to be specified)



- Conditioning events (hypotheses) correspond to histories:

$$[\mathbf{h}] = \{\omega : \pi(\xi(\omega)) \in \mathbf{Z}(\mathbf{h})\}$$

- Probability measures concentrated on conditioning events  $\mathbf{C} = [\mathbf{h}]$ ,  $\mathbf{D} = [\mathbf{h}']$  ... related by chain rule:

$$\mathbf{E} \subset \mathbf{C} \subset \mathbf{D} \Rightarrow \mu(\mathbf{E}|\mathbf{D}) = \mu(\mathbf{E}|\mathbf{C})\mu(\mathbf{C}|\mathbf{D}) \quad (\text{ch.r})$$

- Axiomatization: decision-theoretic (Myerson, 1991, Siniscalchi 2011), epistemic (Di Tillio-Halpern-Samet, 2010)  $\Rightarrow$  Fairly well understood epistemic analysis of conditionals.
- $\Delta_i = \Delta^H(\Omega) \subset [\Delta(\Omega)]^H$ , CPS's on  $(\Omega, \mathbf{H})$ : set of  $(\mathbf{p}_i(\cdot|[\mathbf{h}]))_{\mathbf{h} \in \mathbf{H}} \in [\Delta(\Omega)]^H$  s.t.  $\mathbf{p}_i([\mathbf{h}]|[\mathbf{h}]) = \mathbf{1}$  and (ch.r) holds

We focus on epistemic **type structures** with ext.states  $\mathbf{X} = \mathbf{Z}$ :

$$\Omega = \mathbf{Z} \times \prod_i \mathbf{T}_i, \quad \beta_i : \mathbf{T}_i \rightarrow \Delta^H(\mathbf{Z} \times \mathbf{T}_{-i}), \quad \xi = \zeta = \text{proj}_{\mathbf{Z}},$$

$$\hat{\beta}_i(\mathbf{z}, \mathbf{t}_i, \mathbf{t}_{-i})(\mathbf{E}|\mathbf{[h]}) = \beta_i(\mathbf{t}_i)(\mathbf{E}_{\mathbf{t}_i}|\mathbf{Z}(\mathbf{h}) \times \mathbf{T}_{-i})$$

meaning:

- **no knowledge** about  $\mathbf{z}$  at the outset
- **information** about moves **cannot disclose** anything about types/**beliefs**

Technical (in a sense, w.l.o.g.)

- $\forall i, \mathbf{T}_i$  **compact metrizable**,  $\Rightarrow \Delta^H(\mathbf{Z} \times \mathbf{T}_{-i})$  compact metrizable
- $\beta_i$  **continuous**

## Definition

A structure is *complete* if  $\beta_i$  is **onto** for every  $i \in \mathbf{I}$  (e.g., the *canonical* structure)

Standard (monotonic) belief operators

- conditional belief  $B_i(\mathbf{E}|\mathbf{h}) = \{\omega : \hat{\beta}_i(\mathbf{E}|\mathbf{h}) = \mathbf{1}\}$ ,
- initial belief  $B_i(\mathbf{E}) = B_i(\mathbf{E}|\Omega)$  ( $\Omega = [\phi]$ ,  $\phi$ =empty hist., root)

Nonmonotonic belief operator

- strong belief  $SB_i(\mathbf{E}) = \bigcap_{\mathbf{h}:\mathbf{E}\cap[\mathbf{h}]\neq\emptyset} B_i(\mathbf{E}|\mathbf{h})$

# Setup

## Dynamic programming

Given  $\mathbf{p} \in \Delta^{\mathbf{H}}(\Omega)$  derive

$$\mathbf{p}(\mathbf{a}|\mathbf{h}) = \mathbf{p}([\mathbf{h}, \mathbf{a}]|[\mathbf{h}])$$

for all  $\mathbf{h} \in \mathbf{H} \setminus \mathbf{Z}$ ,  $\mathbf{a} \in \mathbf{A}(\mathbf{h})$ .

Consider only the conditional prob. of  $i$ 's opponents' actions:

$$\mathbf{p}(\mathbf{a}|\mathbf{h}), \mathbf{h} \in \mathbf{H}_{-i}, \mathbf{a} \in \mathbf{A}(\mathbf{h})$$

$\Rightarrow$  subjective decision tree  $\Gamma_i(\mathbf{p})$  for  $i$

$\mathbf{p}$  is consistent with dynamic programming on  $\Gamma_i(\mathbf{p})$  iff (OSD)

$$\forall \mathbf{h} \in \mathbf{H}_i, \mathbf{p} \left( \arg \max_{\mathbf{a} \in \mathbf{A}(\mathbf{h})} \mathbf{V}_i((\mathbf{h}, \mathbf{a}), \mathbf{p}) | \mathbf{h} \right) = 1,$$

$$\text{with } \mathbf{V}_i((\mathbf{h}, \mathbf{a}), \mathbf{p}) = \sum_{\mathbf{z} \in \mathbf{Z}(\mathbf{h}, \mathbf{a})} \mathbf{u}_i(\mathbf{z}) \mathbf{p}(\mathbf{z} | \mathbf{h}, \mathbf{a})$$

# Strategies as beliefs

## Rational planning

The plan of  $i$  at  $(z, t_i, t_{-i})$  (plan of  $t_i$ ) is derived from  $\beta_i(t_i)$

### Definition

Pl.  $i$  plans rationally at  $(z, t_i, t_{-i})$  if

$$\forall h \in H_i, \beta_i(t_i) \left( \arg \max_{a \in A(h)} V_i((h, a), p) | h \right) = 1.$$

Event:  $RP_i$

- $RP_i$  is just a property of  $i$ 's beliefs/types:  $i$  expects to take locally maximizing actions conditional on each  $h \in H_i$ .
- **Interpretation:**  $i$  has beliefs about others and computes his plan (beliefs about himself) by dynamic programming on the corresponding subjective decision tree.

# Strategies as beliefs

## Material Consistency and Material Rationality

Connect beliefs to behavior:

### Definition

Pl.  $i$  is *materially consistent* at  $(z, t_i, t_{-i})$  if he does not violate his plan on path  $z$

$$\forall h \in H_i, \forall a \in A(h), \\ (h, a) \preceq z \Rightarrow \beta_i(t_i)(a|h) > 0.$$

Event:  $MC_i$

### Definition

Pl.  $i$  is *materially rational* at  $(z, t_i, t_{-i})$  if he plans rationally and does not violate his plan at  $(z, t_i, t_{-i})$ . Event:  $MR_i = MC_i \cap RP_i$ .

# Strategies as beliefs

Common belief in MR and Nash equilibrium

- Recall: results apply to **finite PI games with NRT**, in such games the **BI strategy is unique** and (mixed) **Nash equilibria yield a unique path** with prob. 1.
- Similar to traditional analysis: initial common belief in material rationality does not yield BI or Nash paths in games of depth  **$d > 2$**  (e.g. Centipede).

- *Unlike traditional analysis:* in games of **depth 2**, correct belief in rationality does **not** yield **BI**, only a **Nash path** (cf. initial example).

## Proposition

In a game  $\Gamma$  of depth 2,  $\forall z \in \mathbf{Z}$ ,  $z$  is a Nash path if and only if

$$(z, \mathbf{t}) \in \bigcap_i \mathbf{MR}_i \cap \mathbf{B}_i(\mathbf{MR}_{-i})$$

for some  $\mathbf{t}$ , in some type structure  $(\mathbf{T}_i, \beta_i)_{i \in I}$  for  $\Gamma$ .



# Strategies as beliefs

## Common Strong Belief in Material Rationality

- One way to obtain elementary BI (games of depth 2) is to assume that the first mover strongly believes in the material rationality of the co-player.
- We can go further and replicate "traditional" results on common strong belief in rationality and Nash eq. (Battigalli-Friedenberg, 2010), or EFR and BI in complete structures (Battigalli-Siniscalchi, 2002).

# Strategies as beliefs

## Common Strong Belief in Material Rationality

- $MR_i^0 = MR_i$ ,  $MR_i^{k+1} = MR_i^k \cap SB_i(MR_{-i}^k)$
- $CSBMR = \bigcap_{k,i} MR_i^k$ , correct Common Strong Belief in MR
- $\pi : \mathbf{S} \rightarrow \mathbf{Z}$  strategy-path function

### Proposition

(i) In any type structure

$$proj_{\mathbf{Z}} CSBMR \subset \{\mathbf{Nash-paths}\}$$

(ii) In a **complete** (or otherwise "sufficiently rich") structure

$$proj_{\mathbf{Z}} CSBMR = \pi(\mathbf{EFR}) = \{\mathbf{BI-path}\}.$$

# Strategies as beliefs

## Own Action Independence

- Reason for non-BI result: Ann may initially believe in  $\mathbf{MR}_{\text{Bob}}$  but she need not believe in  $\mathbf{MR}_{\text{Bob}}$  conditional on taking an unplanned action.
- This cannot happen if Ann's beliefs about Bob's type *conditional on her own actions* do not depend on the conditioning action, and she strongly (hence always) believes in  $\mathbf{MC}_{\text{Bob}}$ .
- *Own-action independence* =  $\mathbf{i}$ 's conditional beliefs about  $\mathbf{t}_{-i}$  do not depend on  $\mathbf{i}$ 's actions (event  $\mathbf{Ind}_i$ )

## Proposition

*In every "rich" (e.g., complete) type structure for a game of depth 2*

$$\text{proj}_Z \left( \bigcap_i \mathbf{MR}_i \cap \mathbf{Ind}_i \cap \mathbf{B}_i(\mathbf{MR}_{-i}) \cap \mathbf{SB}_i(\mathbf{MC}_{-i}) \right) = \{\mathbf{BI-path}\}.$$

What about longer games (e.g. Centipede)?

# Strategies as beliefs

## Independence

- $\text{MRInd}_i^0 = \text{MR}_i \cap \text{Ind}_i \cap \text{SB}_i(\text{MC}_{-i}),$
- $\text{MRInd}_i^{k+1} = \text{MRInd}_i^k \cap \text{B}_i(\text{MRInd}_{-i}^k)$
- $\text{CBMRInd} = \bigcap_{i,k} \text{MRInd}_i^k$

All the paths consistent with the "Dekel-Fudenberg procedure",  $\pi(\mathbf{S}^\infty \mathbf{W})$ , are also consistent with **CBMRInd** (cf. Ben Porath, 1997):

### Proposition

*For every  $\mathbf{s} \in \mathbf{S}^\infty \mathbf{W}$  there is a type structure with a state  $(\mathbf{z}, \mathbf{t}) \in \text{CBMRInd}$  such that  $\mathbf{z} = \pi(\mathbf{s})$ .*

### Corollary

*There are non-BI paths consistent with **CBMRInd** in Centipede (of depth  $\mathbf{d} > 2$ ).*

- Many results of the “traditional analysis” with behavioral conditionals make a lot of sense. They are built on often implicit assumptions of plan/behavior consistency, strong belief in consistency (perceived intentionality) and self/opponents independence.
- We rule out behavioral conditionals, but allow for epistemic ones. This forces an interpretation of strategies as epistemic constructs.
- Consistency and independence have to be assumed explicitly. This seems fitting for a formal analysis of strategic reasoning.

# Conclusions

Imperfect information (with perfect recall)

- $\mathbf{h}_i \in \mathbf{H}_i$  information sets (personal histories)
- Conditions/hypotheses for  $\mathbf{i}$ :  $[\mathbf{h}_i]$  and  $[\mathbf{h}_i, \mathbf{a}_i]$  ( $\mathbf{a}_i \in \mathbf{A}_i(\mathbf{h}_i)$ )
- Value of action  $\mathbf{a}_i$  at  $\mathbf{h}_i$ :  $\mathbb{E}_{\beta_i(\omega)}[\mathbf{u}_i | \mathbf{h}_i, \mathbf{a}_i]$
- "Newcomb paradoxes"  $\Rightarrow$  potential conflict between our analysis and standard decision theory
- Own-action independence and strong belief in material consistency allow to reconcile our analysis with traditional decision theory.

# Conclusions

## Emerging broad picture

Under consistency and independence we obtain analogs of the “traditional results”.





For generic PI games:






any type structure	complete structure
$\mathbf{CBMRInd} \approx \mathbf{S}^\infty \mathbf{W}$ (?)	$\text{proj}_Z \mathbf{CBMRInd} \supset \pi(\mathbf{S}^\infty \mathbf{W})$ (=?)
$\mathbf{CBMRInd} \approx \mathbf{BI}$ if depth=2	$\mathbf{CSBMR} \approx \mathbf{EFR}$ ( $\approx \mathbf{BI}$ if $d = 2$ )
$\mathbf{CSBMR} \approx \mathbf{Nash}$ path	$\text{proj}_Z \mathbf{CSBMR} = \pi(\mathbf{EFR}) = \{z^{\mathbf{BI}}\}$
$\text{proj}_Z \mathbf{CSBMR} = \{z^{\mathbf{BI}}\}$ in Centip.	$\mathbf{CSBMR} \approx \mathbf{BI}$ in Centipede

( $\approx$  means “characterization w/ strategies as beliefs”, (?)=conj.,  
 $z^{\mathbf{BI}} = \mathbf{BI}$ -path)

We conjecture that the results on  $\mathbf{S}^\infty \mathbf{W}$  and  $\mathbf{EFR}$  can be extended to all games with perfect recall (assuming OAI).



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