

Transparent Restrictions on Beliefs and Forward-Induction Reasoning in Games with Asymmetric Information

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Introduction

- ▶ Overall project: analysis of higher-order beliefs and *forward induction* (FI) reasoning in dynamic games (see Battigalli & Siniscalchi JET 2002, Battigalli & Friedenberg TE 2012)
- ▶ This paper:
 1. (partially) new epistemic justification of the Δ -rationalizability solution concept (version of Battigalli RE 2003)
 2. equivalence of two sets of epistemic assumptions representing FI reasoning and justifying Δ -rationalizability
 3. if restricted belief set Δ is "closed under compositions", Δ -rationalizability is shown to be equivalent to a simpler algorithm used by Battigalli & Siniscalchi BJTE 2003
 4. general analysis: incomplete information, imperfect asymmetric observation of past actions, chance moves

Example: Costly lies (Beer-Quiche in disguise)

- ▶ Chance chooses with prob. $\frac{1}{3} : \frac{2}{3}$ whether Adam (pl. 1) has low productivity (θ^L) or high productivity (θ^H).
- ▶ Adam observes this and then tells Bea (pl. 2) "I am high" (H) or "I am Low" (L). He incurs a small psychological cost c for lying ($c < \frac{1}{3}$).
- ▶ Bea can hire Adam (h) or leave him alone (ℓ).
- ▶ Adam would like to be hired. For Bea, h is a bet on the type of Adam.

The ugly picture

$$\begin{array}{ccccccc}
 \begin{pmatrix} 1-c \\ 1 \end{pmatrix} & \swarrow h & & L & & \theta^H & & H & & h \nearrow & \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\
 & & 2 & \longleftarrow - - - & & 1 - - - & & \longrightarrow & & 2 & \\
 \begin{pmatrix} -c \\ 0 \end{pmatrix} & \swarrow \ell & : & & & \uparrow \frac{2}{3} & & & & : & \ell \searrow & \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\
 & & : & & & \circ & & & & : & & \\
 \begin{pmatrix} 1 \\ -1 \end{pmatrix} & \swarrow h & : & & & \downarrow \frac{1}{3} & & & & : & h \nearrow & \begin{pmatrix} 1-c \\ -1 \end{pmatrix} \\
 & & 2 & \longleftarrow - - - & & 1 - - - & & \longrightarrow & & 2 & \\
 \begin{pmatrix} 0 \\ 0 \end{pmatrix} & \swarrow \ell & & & L & & \theta^L & & H & & \ell \searrow & \begin{pmatrix} -c \\ 0 \end{pmatrix}
 \end{array}$$

Figure 1. Costly lies.

FI epistemic assumptions (informal)

- ▶ Players have beliefs about everything, chance, each other's strategies, and each other's beliefs; they update according to the rules of conditional probabilities whenever they apply (denominator $\neq 0$).
- ▶ First-order restr. (C): Initial beliefs about chance are $\frac{1}{3} : \frac{2}{3}$.
- ▶ First-order restr. (I): Adam regards θ and s_2 as *independent*: his conjecture on s_2 is independent of θ .
- ▶ (C) and (I) are "commonly believed at each node":
transparency of restrictions.
- ▶ Given this, **best rationalization principle**: each player (Bea in particular) always ascribes to the other the "highest degree of strategic sophistication" consistent with what s/he observes (Battigalli GEB 1996).

Step-by-step FI analysis of "Costly Lies"

1. Adam would lie only to maximize the (subjective) probability of being hired, which is *independent* of θ [see (I)]: he sends the maximizing message $m \in \{H, L\}$ when $\theta = \theta^m$. Hence he either pools on one message, or is truthful.
2. If Bea hears H , *even if surprised*, she infers that Adam is either pooling on H or is truthful (best rationalization of H). Hence *the ex ante more likely type, θ^H , becomes even more likely*: $\mu_B(\theta^H | H) \in [\frac{2}{3}, 1]$ [see (C)] and she hires Adam.
3. Adam does not pool on L : he tells the truth if θ^H .
4. If Bea hears L , even if surprised, she infers that Adam is truthtelling (best rationalization of L) and leaves him alone. The strategy of Bea is " h if H , ℓ if L ".
5. Adam pools on H . END

Note: Bea would definitely be surprised by L . Still, she would reason and choose as in 4 (best rationalization).

Formal theory of FI: ingredients

- ▶ *Types structures for dynamic games*, focus on *canonical* structure (Battigalli & Siniscalchi JET 1999): information sets $h \in H_i$, belief maps from types to Cond. Prob. Systems about others

$$\beta_i = (\beta_{i,h})_{h \in H_i} : T_i \rightarrow CPS(\Omega_{-i}, H_i)$$

- ▶ **Conditional belief**: type t_i **believes** E **given** information set $h \in H_i$ if $\beta_{i,h}(t_i)(E) = 1$; *monotone* operator $B_{i,h}(E)$
- ▶ **Full belief**: t_i believes E conditional on each $h \in H_i$; *monotone* operator $B_i(E) = \bigcap_h B_{i,h}(H)$
- ▶ **Strong belief**: t_i **strongly believes** E if he believes E whenever possible: $E \cap [h] \neq \emptyset \Rightarrow \beta_{i,h}(E) = 1$; *non monotone* operator $SB_i(E)$
- ▶ Non-monotonicity of $SB_i(\cdot)$ makes the analysis more interesting and more difficult

Fl reasoning: canonical structure

- ▶ With the canonical structure the analyst must state explicitly as an event assumptions about what is commonly believed
- ▶ Belief restrictions Δ , assumed *compact* (e.g. independence + prob. of chance moves are such and such), event $[\Delta]$
- ▶ **Transparency of Δ** : $B^*([\Delta]) = \bigcap_{n \geq 0} B^n([\Delta])$; note:
 $B^*([\Delta]) = [\Delta] \cap B(B^*([\Delta])) = \times_{i \in I} B_i^*([\Delta])$
- ▶ **Rationality**: conditional max. of EU, event R_i
- ▶ **Rat. $\cap B^*([\Delta])$ and Common Strong Belief of Rat. $\cap B^*([\Delta])$**

$$\begin{aligned}R_{i,\Delta}^1 &= R_i \cap B_i^*([\Delta]) \\ R_{i,\Delta}^{m+1} &= R_{i,\Delta}^m \cap SB_i(R_{-i,\Delta}^m) \\ RCSBR_{\Delta} &= \times_{i \in I} \bigcap_{m \geq 1} R_{i,\Delta}^m\end{aligned}$$

Intermezzo: an equivalent approach

- ▶ $B^*([\Delta])$ yields a type structure \mathcal{T}_Δ^* embedded in the canonical structure \mathcal{T}^* . Define events within any type structure \mathcal{T}_Δ hierarchy-equivalent to \mathcal{T}_Δ^* .
- ▶ Transparency of Δ is captured implicitly within \mathcal{T}_Δ .
- ▶ **Rationality** within \mathcal{T}_Δ : conditional max. EU, event $R_{i,\Delta}$
- ▶ **Rationality and Common Strong Belief in Rationality** within \mathcal{T}_Δ

$$\begin{aligned}R_{i,\Delta}^1 &= R_{i,\Delta} \\R_{i,\Delta}^{m+1} &= R_{i,\Delta}^m \cap \text{SB}_i(R_{-i,\Delta}^m) \\CSBR_\Delta &= \times_{i \in I} \cap_{m \geq 1} R_{i,\Delta}^m\end{aligned}$$

FI rationalizability solution: ingredients

- ▶ Players $i \in I$, information types (e.g. payoff types) $\theta_i \in \Theta_i$, information sets $h \in H_i$, strategies $s_i \in \times_{h \in H_i} A_i(h)$, chance is pl. $0 \notin I$, here $-i = (I \cup \{0\}) \setminus \{i\}$
- ▶ Iterated deletion of pairs (θ_i, s_i) for each $i \in I$
- ▶ First-order beliefs μ_i on $\Theta_{-i} \times S_{-i}$, restrictions may depend on θ_i :

$$\mu_i = (\mu_{i,h})_{h \in H_i} \in \Delta_{\theta_i} \subseteq CPS(\Theta_{-i} \times S_{-i}, H_i)$$

- ▶ BR correspondence

$$r_{\theta_i}(\mu_i) = \{s_i \in S_i : s_i \text{ is sequential BR for } \theta_i \text{ to } \mu_i\}$$

FI rationalizability: algorithm

- ▶ $\Delta_{\theta_i}^0 = \Delta_{\theta_i}$
- ▶ given $\Delta^n = \left(\Delta_{\theta_j}^n \right)_{j \in I, \theta_j \in \Theta_j}$, let

$$\Sigma_{0, \Delta}^{n+1} = \Theta_0 \times S_0 \text{ (no } (\theta_0, s_0) \text{ is ever deleted)}$$

$$\Sigma_{i, \Delta}^{n+1} = \{(\theta_i, s_i) : s_i \in r_{\theta_i}(\Delta_{\theta_i}^n)\} \quad (i \in I)$$

$$\Delta_{\theta_i}^{n+1} = \left\{ \mu_i \in \Delta_{\theta_i}^n : \forall h \in H_i, \Sigma_{-i}^{n+1} \cap \Sigma_{-i}(h) \neq \emptyset \Rightarrow \mu_{i,h}(\Sigma_{-i}^{n+1}) = 1 \right\}$$

- ▶ Note: $\Sigma_{i, \Delta}^n$ may be empty if Δ features some restrictions to endogenous beliefs, due to possible conflict between belief restrictions and strategic reasoning

A simpler algorithm

Battigalli & Siniscalchi BEJTE 2003 consider a simpler algorithm, closer to Pearce ECMA 1984 (who implicitly assumes as restrictions only the known probabilities of chance moves)

- ▶ $\hat{\Sigma}_{i,\Delta}^0 = \Theta_i \times S_i$
- ▶ given $(\hat{\Sigma}_{i,\Delta}^n)_{i \in I \cup \{0\}}$

$$\hat{\Sigma}_{0,\Delta}^{n+1} = \Theta_0 \times S_0 \text{ (no } (\theta_0, s_0) \text{ is ever deleted)}$$

$$\hat{\Sigma}_{i,\Delta}^{n+1} = \left\{ (\theta_i, s_i) \in \hat{\Sigma}_{i,\Delta}^n : \begin{array}{l} \exists \mu_j \in \Delta_{\theta_i}, s_i \in r_{\theta_i}(\mu_j), \forall h \in H_i, \\ \hat{\Sigma}_{-i,\Delta}^n \cap \Sigma_{-i}(h) \neq \emptyset \Rightarrow \mu_{i,h}(\hat{\Sigma}_{-i,\Delta}^n) = 1 \end{array} \right\}$$

Comparison

- ▶ Note subtle difference: the def. of $\hat{\Sigma}_{i,\Delta}^n$ does *not* require μ_i to satisfy the best rationalization principle w.r.t. $(\hat{\Sigma}_{-i,\Delta}^m)_{m=1}^{m=n}$, endogenous restrictions on beliefs from previous steps can be ignored (making the algorithm simpler)
- ▶ In general, $\Sigma_{i,\Delta}^2 = \hat{\Sigma}_{i,\Delta}^2$, $\Sigma_{i,\Delta}^3 \subseteq \hat{\Sigma}_{i,\Delta}^3$, possibly $\Sigma_{i,\Delta}^n \subsetneq \hat{\Sigma}_{i,\Delta}^n$ for $n > 3$ due to non-monotonicity of strong belief
- ▶ Differences may follow from the failure of Δ_i to contain "compositions" of CPS's in Δ_i
- ▶ The price of greater simplicity is that the algorithm is not "conceptually correct", i.e. there is some Δ such that $(\Sigma_{\Delta}^n)_{n \in \mathbb{N}}$ does not capture what it is meant to.

Main result

Behavioral predictions of epistemic assumptions $EA = \times_{i \in I} EA_i$
given by $\text{proj}_{\Theta_i \times S_i} EA_i$

Theorem

For every $i \in I$ and $m \in \mathbb{N}$

$$\text{proj}_{\Theta_i \times S_i} R_{i,\Delta}^m = \Sigma_{i,\Delta}^m$$

Hence

$$\text{proj}_{\Theta \times S} RCSBR_{\Delta} = \Sigma_{\Delta}^{\infty}$$

Alternative epistemic justification of FI rationalizability

- ▶ See Battigalli & Siniscalchi RE 2007, "the sausage" for friends and family :-)

$$\hat{R}_{i,\Delta}^1 = R_i \cap [\Delta_i]$$

(note: $B_i^*([\Delta]) \subseteq [\Delta_i]$, hence $R_{i,\Delta}^1 = R_i \cap B_i^*([\Delta]) \subseteq \hat{R}_{i,\Delta}^1$)

$$\hat{R}_{i,\Delta}^{m+1} = \hat{R}_i^m \cap SB_i(\hat{R}_{-i,\Delta}^m)$$

- ▶ Although $R_{i,\Delta}^1 \subseteq \hat{R}_{i,\Delta}^1$, $R_{i,\Delta}^m \subseteq \hat{R}_{i,\Delta}^m$ cannot be proved using standard monotonicity arguments because SB_i is not monotone. But ...
- ▶ B&S 2007 shows (essentially) $\text{proj}_{\Theta_i \times S_i} \hat{R}_{i,\Delta}^m = \Sigma_{i,\Delta}^{m+1}$ for every i and m . Hence

Theorem

For every $i \in I$ and $m \in \mathbb{N}$

$$\begin{aligned} \text{proj}_{\Theta_i \times S_i} R_{i,\Delta}^m &= \Sigma_{i,\Delta}^m = \text{proj}_{\Theta_i \times S_i} \hat{R}_{i,\Delta}^m \\ R_{i,\Delta}^m &\subseteq \hat{R}_{i,\Delta}^m \end{aligned}$$






Results about algorithms

- ▶ It can be easily be shown by example that $(\hat{\Sigma}_{\Delta}^n)_{n \in \mathbb{N}}$ may be different from the conceptually correct algorithm $(\Sigma_{\Delta}^n)_{n \in \mathbb{N}}$.
- ▶ Furthermore, for some game and restrictions Δ there is no type structure T such that $\text{proj}_{\Theta \times S} \text{RCSBR}_T = \Sigma_{\Delta}^{\infty}$, i.e. Σ_{Δ}^{∞} is not an "extensive form best response set". Thank you Amanda Friedenberg :-)
- ▶ We define the property " Δ_i is closed under compositions" so that:
Proposition *If Δ_i is closed under compositions for every $i \in I$, then $\hat{\Sigma}_{\Delta}^n = \Sigma_{\Delta}^n$ for every $n \in \mathbb{N}$.*
- ▶ The property is satisfied in many applications of interest:
 - ▶ Δ_i only captures restrictions on exogenous beliefs (beliefs about θ_{-i} and chance moves)
 - ▶ Δ_i only captures restrictions on initial beliefs (e.g. consistency with a distribution of paths) and/or independence restrictions (connection with FI refinements of Nash eq. based on strategic stability)






I never have time for conclusions

Thank you for your patience

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