LECTURES 6 Markov chains

Macroeconomics 4

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L6: Markov chains

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- A time-invariant, discrete-state Markov chain is characterized by:
 - An *n*-dimensional state space $S = \{s_1, s_2, ..., s_n\}$.
 - A $n \times n$ non-negative transition matrix Π , such that $\sum_{j=1}^{n} \Pi_{ij} = 1$ for i = 1, 2, ..., n.
 - A $n \times 1$ non-negative vector π_0 , such that $\sum_{i=1}^n \pi_{0,i} = 1$, representing the initial (unconditional) probability distribution on s_0 :

$$\pi_{0,i} = \operatorname{prob}\left(s_0 = \mathbf{s}_i\right).$$

• The matrix Π is a *right stochastic matrix*, and records the transition prob. from state *i* into state *j*:

$$\Pi_{ij} = \operatorname{prob}\left(s_{t+1} = \mathbf{s}_j | s_t = \mathbf{s}_i\right).$$

• Note that:

$$prob (s_{t+2} = s_j | s_t = s_i)$$

= $\sum_{m=1}^{n} prob (s_{t+2} = s_j | s_{t+1} = s_m) prob (s_{t+1} = s_m | s_t = s_i)$
= $\sum_{m=1}^{n} \prod_{im} \prod_{mj} = \prod_{ij}^{(2)},$

where $\Pi_{ij}^{(2)}$ is the (i, j) element of $\Pi^{(2)}$.

• Hence, in general:

$$\operatorname{prob}\left(s_{t+k} = \mathbf{s}_j | s_t = \mathbf{s}_i\right) = \Pi_{ij}^{(k)}.$$

Definition

State *i* communicates with state *j* if $\Pi_{ij}^{(k)} > 0$ and $\Pi_{ji}^{(k)} > 0$ for some $k \ge 1$. A Markov chain is said to be **irreducible** if every pair (i, j) communicate.

- An irred. Markov chain has the property that it is possible to move from any state to any other in a **countable** number of periods.
- Note that it is not required that this movement is possible in one step, so Π_{ij} = 0 is permitted.

Definition

The **unconditional distribution** of s_t is given by:

$$\pi_t = \left(\Pi'\right)^t \pi_0,$$

where $\pi_{it} = \operatorname{Prob}(s_t = s_i)$.

• Note that:

$$\pi_{t+1} = \Pi' \pi_t.$$

• Trivially:

$$\mathbb{E}\left(s_{t+1} \mid s_t = \mathbf{s}_i\right) = \sum_{j=1}^n \Pi_{ij} s_j,$$
$$\operatorname{var}\left(s_{t+1} \mid s_t = \mathbf{s}_i\right) = \sum_{j=1}^n \Pi_{ij} s_j^2 - \left(\sum_{j=1}^n \Pi_{ij} s_j\right)^2$$

Definition

An unconditional dist. is called **stationary (ergodic)** if it remains constant over time, and satisfies:

$$\pi = \Pi' \pi.$$

• The ergodic dist. can be interpreted in two ways:

- π_i is the unconditional prob. that the chain is currently in state i,
- *π_i* is the prob. that the chain will be in state *i* in *t* steps as *t* → ∞.
 Again, the unconditional moments obtain as:

$$\mathbb{E}(s) = \sum_{j=1}^{n} \pi_j s_j,$$

var $(s) = \sum_{j=1}^{n} \pi_j s_j^2 - \left(\sum_{j=1}^{n} \pi_j s_j\right)^2$

• The stationarity cond. can be rewritten as:

 $\left(\mathbf{1}-\Pi'\right)\pi=\mathbf{0}.$

- In other words, π is just an eigenvector associated with a unit eigenvalue of Π' , pinned down by the normalization $\sum_{j=1}^{n} \pi_j = 1$.
- The matrix Π is **right stochastic**, i.e. has non-negative elements and rows that sum up to one; this implies that:
 - Π' has at least one (possibly more) unit eigenvalue.
 - ▶ There is at least one (again, possibly more) eigenvector satisfying the stat. condition.

Definition

If there is one and only one vector π that satisfies the stat. condition, and:

$$\lim_{t\to\infty}\pi_t=\pi,$$

for all possible π_0 , then the Markov chain is asy. stationary with a unique invariant (ergodic) distribution.

Theorem

Let Π be a right stochastic matrix such that $\Pi_{ij} > 0$ for all (i, j): the associated Markov chain is irreducible, asy. stationary and has a unique stationary distribution.

- From a numerical point of view, there are several ways to calculate π given II.
- 1. Iterate until convergence on:

$$\pi_{k+1} = \Pi' \pi_k.$$

2. Calculate the eigenvalues and eigenvectors of Π' and take the normalized eigenvector associated to $\lambda = 1$:

$$\pi = \frac{v_1}{\sum_{i=1}^n v_{1i}}$$

3. Define:

$$\mathbf{\hat{A}} \equiv \left(\mathbf{A}'\mathbf{A}\right)^{-1}\mathbf{A}',$$

where:

$$\mathbf{A}_{(n+1)\times n} \equiv \left[\begin{array}{c} \mathbf{I}_n - \Pi' \\ \mathbf{1}'_n \end{array} \right],$$

and $\mathbf{1}_n$ is a $n \times 1$ vector of ones; it turns out that π is equal to the n + 1 column of $\hat{\mathbf{A}}$.

4. Note that $\mathbf{1}_{n \times n} \pi = \mathbf{1}_n$, where $\mathbf{1}_{n \times n}$ is a $n \times n$ matrix of ones, since π sums to one. Hence:

$$\mathbf{1}_n = \pi - \Pi' \pi + \mathbf{1}_{n \times n} \pi = \left(\mathbf{I}_n - \Pi' + \mathbf{1}_{n \times n}\right) \pi.$$

This implies that:

$$\pi = \left(\mathbf{I}_n - \Pi' + \mathbf{1}_{n \times n}\right)^{-1} \mathbf{1}_n.$$

• Consider the following stationary AR(1) process:

$$z' = (1 - \rho)\,\mu_z + \rho z + \epsilon,$$

where $|\rho| < 1$ and $\epsilon \sim N(0, \sigma_{\epsilon}^2)$.

• Quite often, in Macro we are required to compute expectations of the form:

$$\mathbb{E}\left[V\left(a',z'\right)\mid z\right] = \int_{-\infty}^{+\infty} V\left(a',z'\right) f\left(z'\mid z\right) dz'.$$

• It would be numerically very convenient if we could discretize the continuous distribution of z.

- In other words, we will approx. the continuous AR(1) with a discrete Markov chain, say z with some abuse of notation, that:
 - takes values in a finite set $\mathcal{Z} = \{z_1, z_2, ..., z_n\},$
 - \blacktriangleright is characterized by a trans. matrix $\Pi.$
- This approx. allows to easily compute the previous expectation as:

$$\mathbb{E}\left[V\left(a',z'\right) \mid \mathbf{z}_{i}\right] = \sum_{j=1}^{n} \Pi_{ij} V\left(a',\mathbf{z}_{j}\right).$$

- To develop an intuition, consider the approach of Tauchen (1986).
- Note that, conditionally on $z, z' \sim N(\mu', \sigma_{\epsilon}^2)$, where $\mu' \equiv (1 \rho) \mu_z + \rho z$.
- Unconditionally, instead, $\mathbb{E}(z) = \mu_z$ and $\operatorname{var}(z) = \sigma_z^2 = \sigma_\epsilon^2 / (1 \rho).$
- The first step requires to select the finite set \mathcal{Z} ; assume that $z_1 < z_2 < ... < z_n$.
- z_1 and z_n are set, respectively, to *m* uncond. std. dev. on either side of μ_z , and the other z_j are spread uniformly over the interval:

$$z_1 = \mu_z - m\sigma_z$$
, $z_n = \mu_z + m\sigma_z$, $z_j = z_1 + \frac{z_n - z_1}{n - 1} (j - 1)$.

• The trans. matrix Π is chosen to match the prob. of moving from z_i into the interval:

$$\left(\mathbf{z}_{j}-\mathbf{w}_{\mathbf{z}},\mathbf{z}_{j}+\mathbf{w}_{\mathbf{z}}\right],$$

where $w_z \equiv \frac{1}{2} \frac{z_n - z_1}{n - 1}$.

• More precisely, we set:

$$\begin{cases} \Pi_{i1} = \operatorname{prob} \left(\mu'_i + \epsilon \leq z_1 + w_z \right), \\ \Pi_{in} = 1 - \operatorname{prob} \left(z_n - w_z < \mu'_i + \epsilon \right), \\ \Pi_{ij} = \operatorname{prob} \left(z_j - w_z < \mu'_i + \epsilon \leq z_j + w_z \right), \end{cases}$$

where $\mu'_i \equiv (1 - \rho) \mu_z + \rho z_i$.

• Operationally, the previous rule boils down to:

$$\Pi_{ij} = \begin{cases} \Phi\left(\frac{\mathbf{z}_1 + \mathbf{w}_z - \mu'_i}{\sigma}\right) & \text{for } j = 1, \\ \Phi\left(\frac{\mathbf{z}_j + \mathbf{w}_z - \mu'_i}{\sigma}\right) - \Phi\left(\frac{\mathbf{z}_j - \mathbf{w}_z - \mu'_i}{\sigma}\right) & \text{for } 1 < j < n, \\ 1 - \Phi\left(\frac{\mathbf{z}_n - \mathbf{w}_z - \mu'_i}{\sigma}\right) & \text{for } j = n. \end{cases}$$

where Φ is the *CDF* of the standard normal.

- Note that m = 1 would cover about 67% of the support of the uncond. dist., m = 2 about 96%, and m = 3 about 99%; the larger m, the larger n has to be to approx. well the conditional moments.
- Tauchen (1986) suggests that rarely n>9 is needed, but notes that the quality of the approx. decreases sharply when $|\rho| \to 1$.

- Tauchen and Hussey (1991) improve on Tauchen (1986) by taking advantage of *Gauss-Hermite (G-H) quadrature*.
- Suppose that $z \sim N(\mu_z, \sigma_z^2)$, i.e. no AR structure.
- Using G-H quadrature, we can approx. the expectation as:

$$\mathbb{E}\left[V\left(a',z'\right)\mid z\right]\approx\frac{1}{\sqrt{\pi}}\sum_{j=1}^{n}\omega_{j}V\left(a',\overline{z}_{j}\right),$$

where $\overline{z}_j \equiv \sqrt{2}\sigma_z h_j + \mu_z$, $\{h_j\}_{j=1}^n$ and $\{\omega_j\}_{j=1}^n$ are, respectively, the G-H nodes (i.e. the roots of the *n*th order *Hermite polynomial*) and weights.

• If z follows an AR(1) process, this would be extremely cumbersome because μ_z , the cond. mean of z', depends on z.

• Note that:

$$\mathbb{E}\left[V\left(a',z'\right)\mid z\right] = \int_{-\infty}^{+\infty} V\left(a',z'\right) \frac{f\left(z'\mid z\right)}{f\left(z'\mid \mu_z\right)} f\left(z'\mid \mu_z\right) dz',$$

where $f(z' \mid \mu_z)$ is the density of z' cond. on $z = \mu_z$.

• The approx. becomes the following:

$$\mathbb{E}\left[V\left(a',z'\right)\mid z\right] \approx \frac{1}{\sqrt{\pi}}\sum_{j=1}^{n}\omega_{j}V\left(a',\overline{z}_{j}\right)\frac{f\left(\overline{z}_{j}\mid z\right)}{f\left(\overline{z}_{j}\mid \mu_{z}\right)}.$$

• For $z = \overline{z}_i$, we have:

$$\mathbb{E}\left[V\left(a',z'\right)\mid \overline{\mathbf{z}}_{i}\right] \approx \sum_{j=1}^{n} \overline{\omega}_{i,j} V\left(a',\overline{\mathbf{z}}_{j}\right),$$

where $\bar{\omega}_{i,j} \equiv \frac{1}{\sqrt{\pi}} \omega_j \frac{f(\bar{z}_j | \bar{z}_i)}{f(\bar{z}_j | \mu_z)}$.

- The previous discussion suggests that the possible realizations of the discrete Markov chain should be \$\mathcal{Z} = {\bar{z}_j}_{i=1}^n\$.
- We cannot use the $\bar{\omega}_{i,j}$ directly in the trans. matrix, because $\sum_{j=1}^{n} \bar{\omega}_{i,j} \neq 1$. Instead, set:

$$\Pi_{ij} = \frac{\omega_{i,j}}{\sum_{j=1}^{n} \bar{\omega}_{i,j}}$$

• Hence:

$$\mathbb{E}\left[V\left(a',z'\right)\mid \overline{z}_{i}\right] \approx \sum_{j=1}^{n} \Pi_{ij} V\left(a',\overline{z}_{j}\right).$$

• Tauchen and Hussey (1991) show that $\lim_{n\to\infty}\sum_{j=1}^{n} \bar{\omega}_{i,j} = 1$ for all *i*, so the prev. approx. converges to *G*-*H* approx. when $n \to \infty$.

- For highly persistent processes (say |ρ| > 0.9), Kopecky and Suen (2010) advocate Rouwenhorst's method.
- The set \mathcal{Z} consists of n points which are symmetrically and evenly spaced over the interval $[\mu_z v, \mu_z + v]$, for some v > 0.
- Choose some p and q in the (0, 1) interval, with possibly p = q.
- For n = 2, the trans. matrix becomes:

$$\Pi_2 = \left[\begin{array}{cc} p & 1-p \\ 1-q & q \end{array} \right]$$

• Π_n for $n \ge 3$ obtains recursively as follows:

▶ 1) Compute:

$$\begin{split} \hat{\Pi}_n &= p \begin{bmatrix} \Pi_{n-1} & \mathbf{0} \\ \mathbf{0}^T & 0 \end{bmatrix} + (1-p) \begin{bmatrix} \mathbf{0} & \Pi_{n-1} \\ 0 & \mathbf{0}^T \end{bmatrix} + \\ & (1-q) \begin{bmatrix} \mathbf{0}^T & \mathbf{0} \\ \Pi_{n-1} & \mathbf{0} \end{bmatrix} + q \begin{bmatrix} \mathbf{0} & \mathbf{0}^T \\ \mathbf{0} & \Pi_{n-1} \end{bmatrix}, \end{split}$$

where **0** is a n - 1 col. vector of zeros.

▶ 2) Divide all but the top and bottom rows of $\hat{\Pi}_n$ by 2 to obtain Π_n .

- Note that setting p different from q would introduce conditional heteroscedasticity in the shocks.
- Regardless of n and Z, the autocor. of this Markov chain is equal to p + q 1; hence, assuming conditional homosced., so that p = q, we set:

$$p = \frac{1+\rho}{2},$$

in order to replicate the persistence of the continuous process.

• The var. of the Markov chain is simply $v^2/(n-1)$; hence, for a given n, in order to replicate the var. of the continuous process we set:

$$\upsilon = \sqrt{\frac{n-1}{1-\rho^2}}\sigma_{\epsilon}.$$

Merging Markov chains

- Suppose that households are subject to two **independent** idiosyncratic shocks, say shocks to labor productivity and preferences.
- The processes are approx. by two discrete Markov chains, $s_t \in \{s_1, s_2\}$ and $z_t \in \{z_1, z_2\}$, characterized respectively by transition matrices Π and Ξ .
- The joint process can be represented a single Markov chain: construct $q_t = (s_t, z_t) \in \{(s_1, z_1), (s_1, z_2), (s_2, z_1), (s_2, z_2)\}.$
- The transition matrix for the joint process becomes:

$$\mathbf{\Lambda} = \begin{bmatrix} \Pi_{11} \Xi_{11} & \Pi_{11} \Xi_{12} & \Pi_{12} \Xi_{11} & \Pi_{12} \Xi_{12} \\ \Pi_{11} \Xi_{21} & \Pi_{11} \Xi_{22} & \Pi_{12} \Xi_{21} & \Pi_{12} \Xi_{22} \\ \Pi_{21} \Xi_{11} & \Pi_{21} \Xi_{12} & \Pi_{22} \Xi_{11} & \Pi_{22} \Xi_{12} \\ \Pi_{21} \Xi_{21} & \Pi_{21} \Xi_{22} & \Pi_{22} \Xi_{21} & \Pi_{22} \Xi_{22} \end{bmatrix}$$

References I

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